

# Big Data



VICTORIA UNIVERSITY OF  
**WELLINGTON**  
TE HERENGA WAKA

**AIML427**

**Manifold Learning/  
Nonlinear Dimensionality Reduction (2)**

Dr Bach Nguyen

(with thanks to Dr Andrew Lensen)

[Bach.Nguyen@vuw.ac.nz](mailto:Bach.Nguyen@vuw.ac.nz)

# t-distributed Stochastic Neighbor Embedding (t-SNE)

- Last lecture, we focused on preserving distances/rankings
- t-SNE instead uses *probability distributions*
  - How likely would you select a point as a neighbour?

"The similarity of datapoint  $x_j$  to datapoint  $x_i$  is the conditional probability,  $p_{j|i}$ , that  $x_i$  would pick  $x_j$  as its neighbour if neighbours were picked in proportion to their probability density under a Gaussian centred at  $x_i$ " [1]

- The “t-” stands for the use of the Student’s  $t$ -distribution

[1] L. Van der Maaten and G. Hinton. "Visualizing data using t-SNE." *Journal of machine learning research* 9(11) (2008)

# Lots of maths, but essentially...

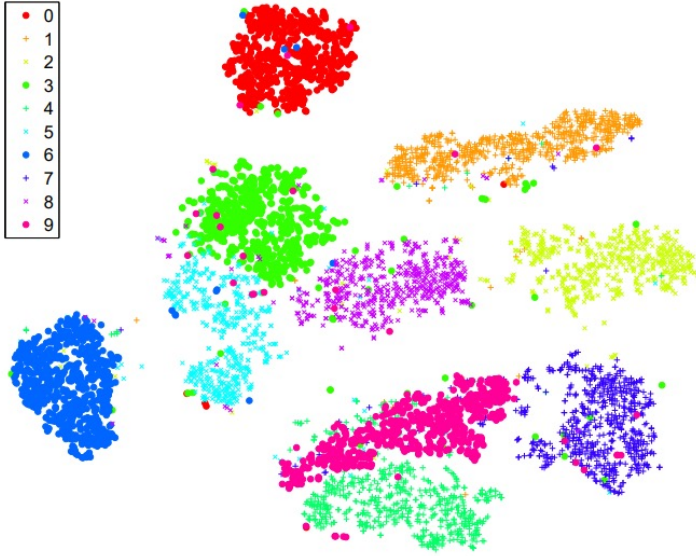
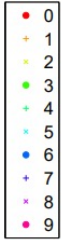
- Calculate neighbour probabilities for each pair of instances
- **Symmetrise**:  $p_{ij} = \frac{p_{j|i} + p_{i|j}}{2N}$  (for  $N$  points)  
(NB:  $p_{ij} = p_{ji}$  and  $p_{ii} = 0$ )
- Set of all  $p_{ij}$  forms  $\mathbf{P}$ , the probability distribution in high-dimensional space
- Use a similar approach to calculate  $\mathbf{Q}$  (low-dim space)

- Optimise by minimising the (Kullback-Leibler) difference between these two distributions:

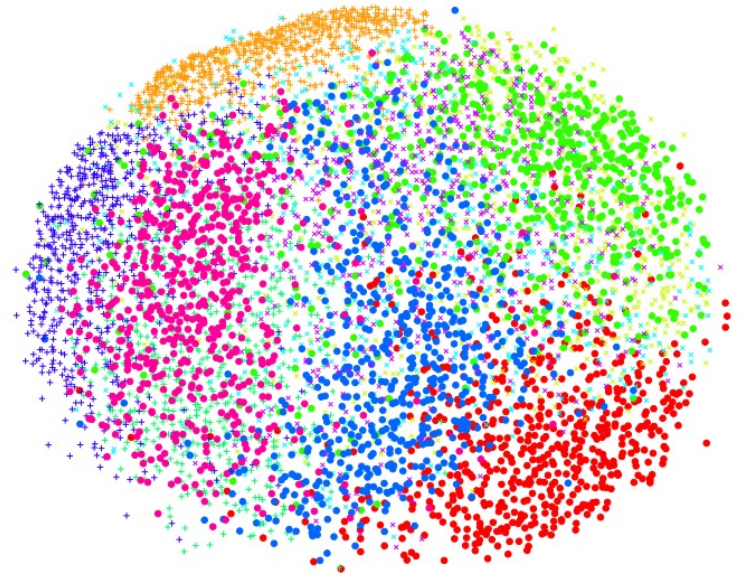
$$KL(P||Q) = \sum_{i \neq j} p_{ij} \log \frac{p_{ij}}{q_{ij}}$$

- Use gradient descent to optimise low-dim space

# So...is it any good?



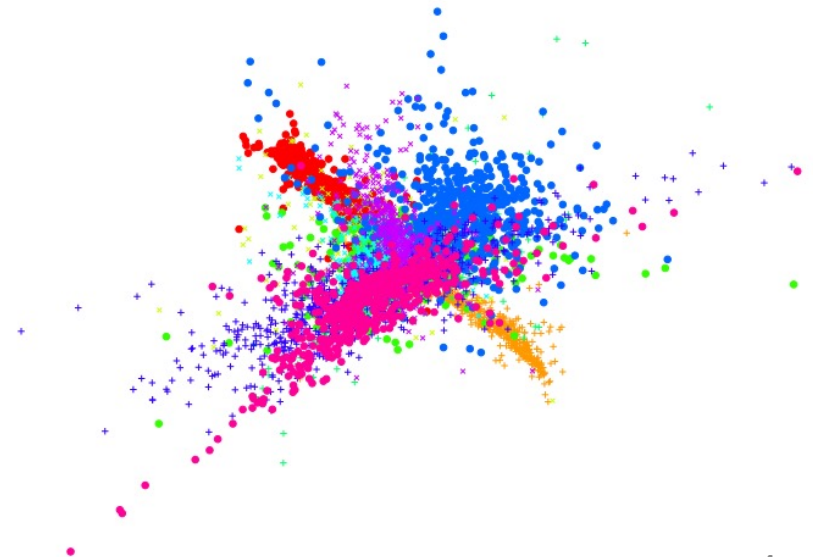
(a) Visualization by t-SNE.



(b) Visualization by Sammon mapping.



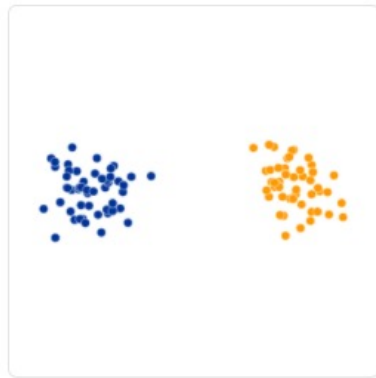
(a) Visualization by Isomap.



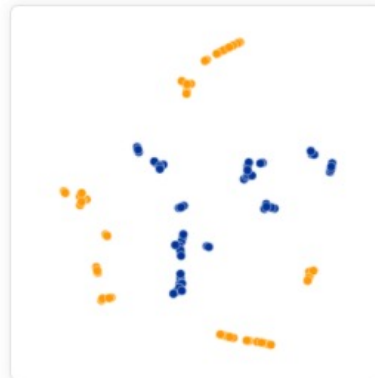
(b) Visualization by LLE.

# t-SNE: issues

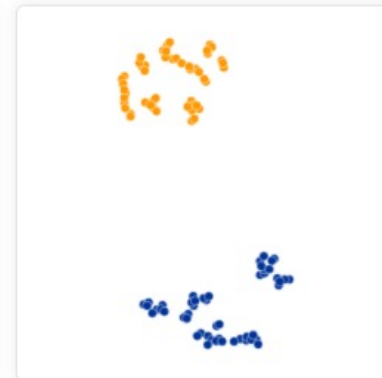
- A **stochastic** algorithm: different results each run
- **Perplexity** parameter balances local vs global structure



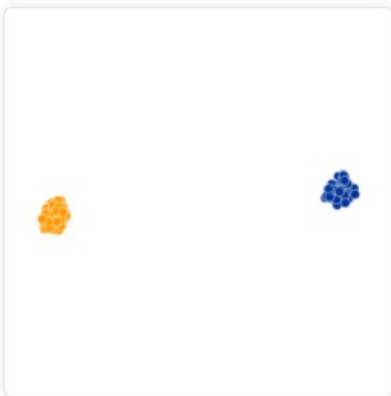
*Original*



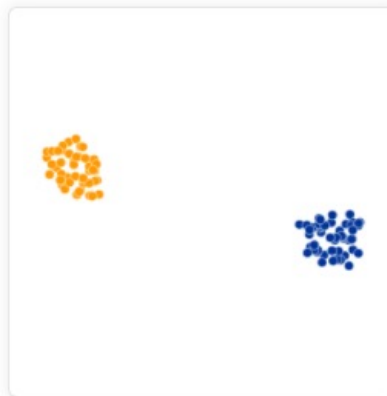
Perplexity: 2  
Step: 5,000



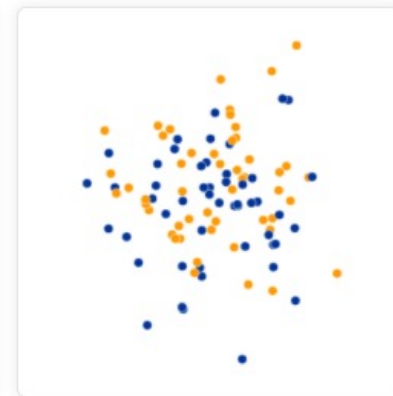
Perplexity: 5  
Step: 5,000



Perplexity: 30  
Step: 5,000



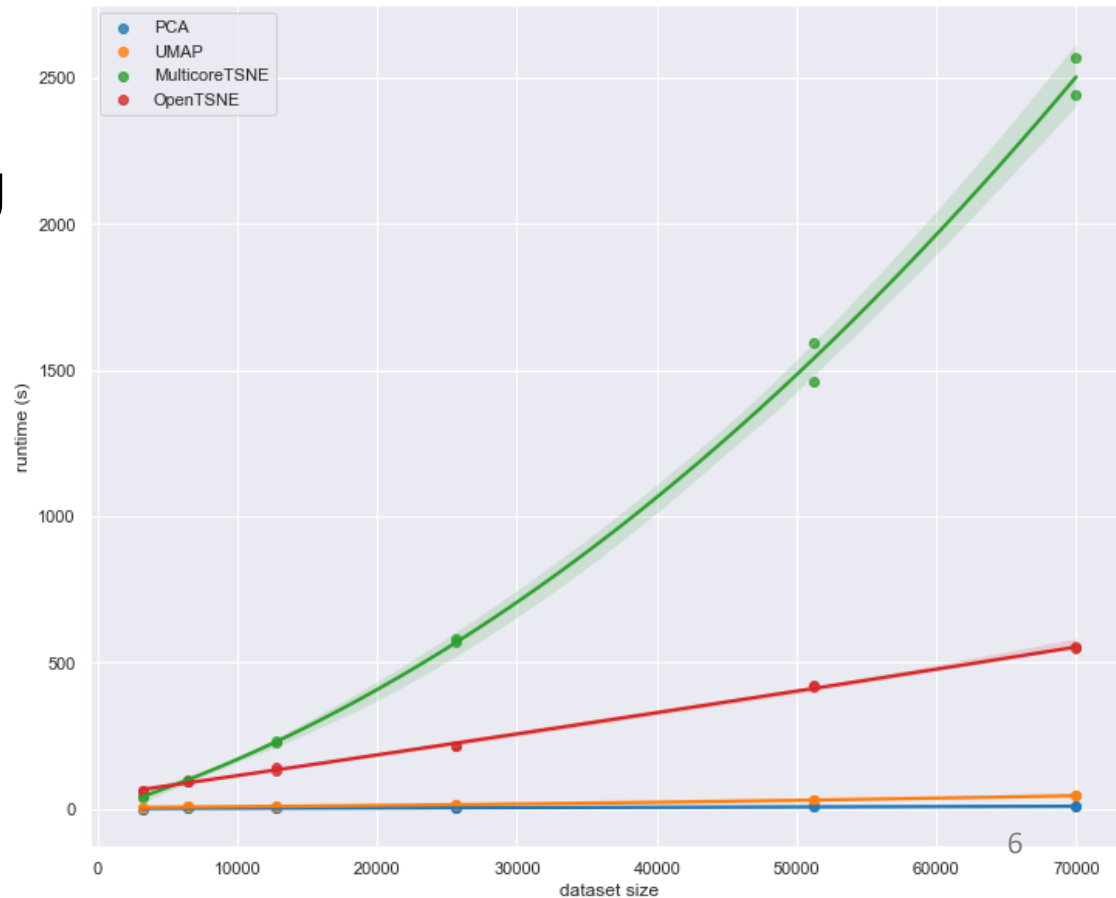
Perplexity: 50  
Step: 5,000



Perplexity: 100  
Step: 5,000

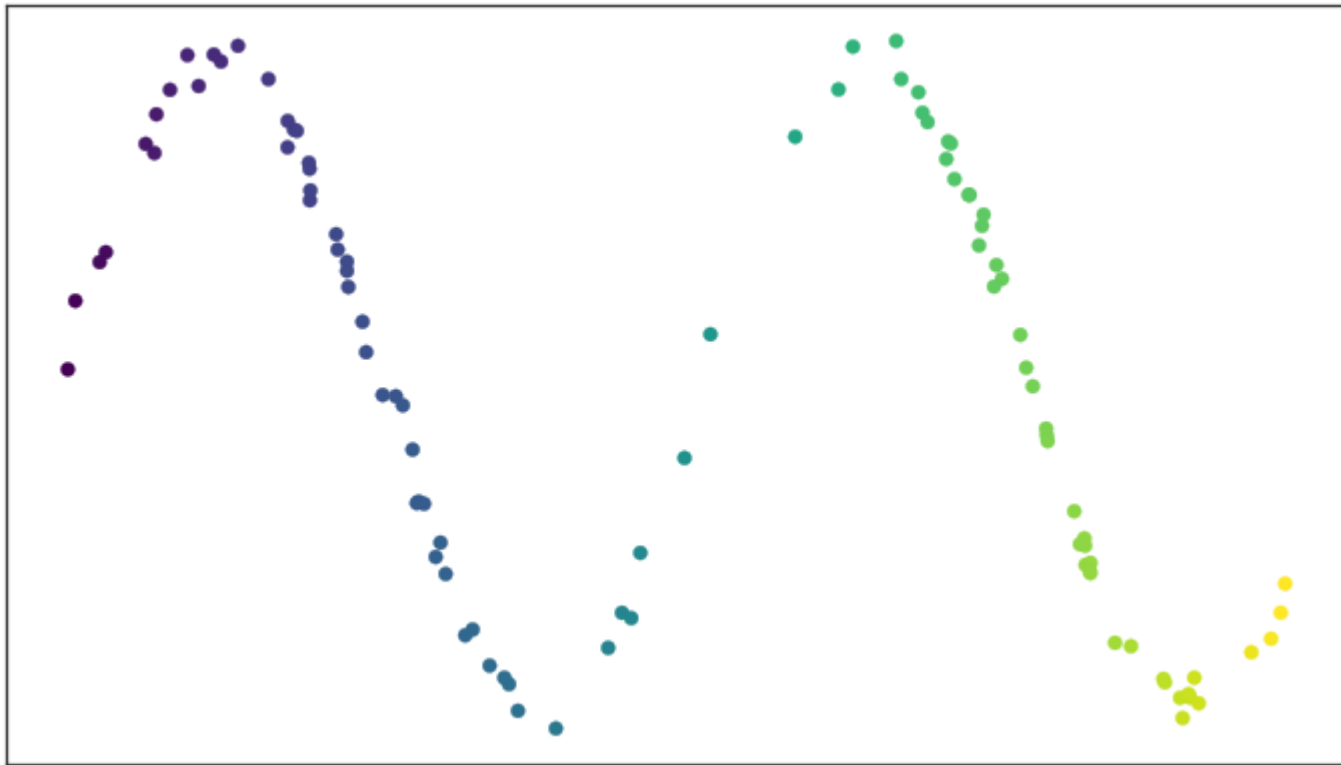
# t-SNE: issues

- First and foremost, designed for **visualisation**
  - Not clear how well it works in  $d > 3$  dimensions
- Hyperparameters can be quite **sensitive**
- **Computationally expensive**
- Still no *mapping* from high-dim to embedding
  - Parametric t-SNE exists, but...
- Was state-of-the-art from **2008** until **2018!**
  - ...and then?



# Uniform Manifold Approximation and Projection for Dimension Reduction (UMAP)

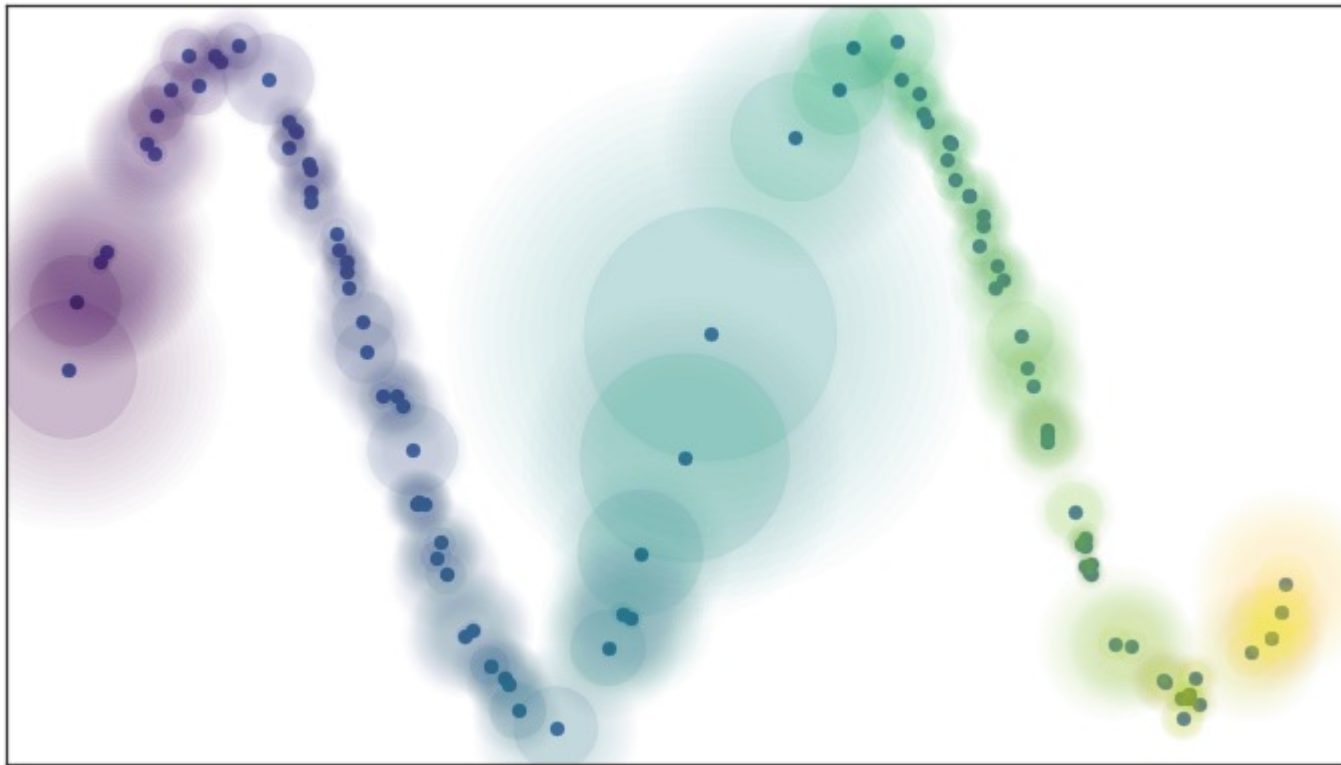
- How does it work? Similar, in ways, to t-SNE
  - Assumes the data is “*uniformly distributed on Riemannian manifold*”



Long version: [https://umap-learn.readthedocs.io/en/latest/how\\_umap\\_works.html](https://umap-learn.readthedocs.io/en/latest/how_umap_works.html)

# UMAP

- Each instance is connected to *at least* its nearest-neighbour
- “Fuzzy” connection to neighbours beyond that
- Focuses on differences in distances, not raw: local topology!

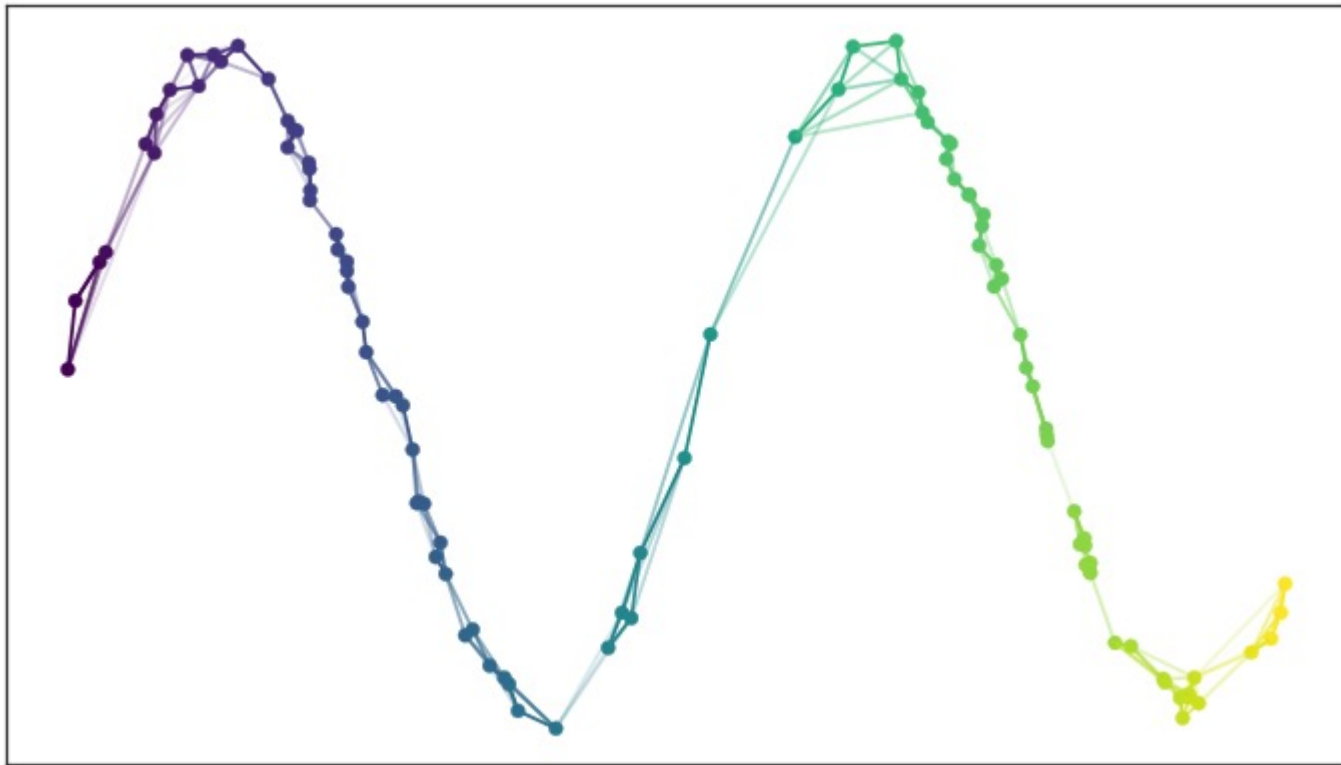


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# UMAP

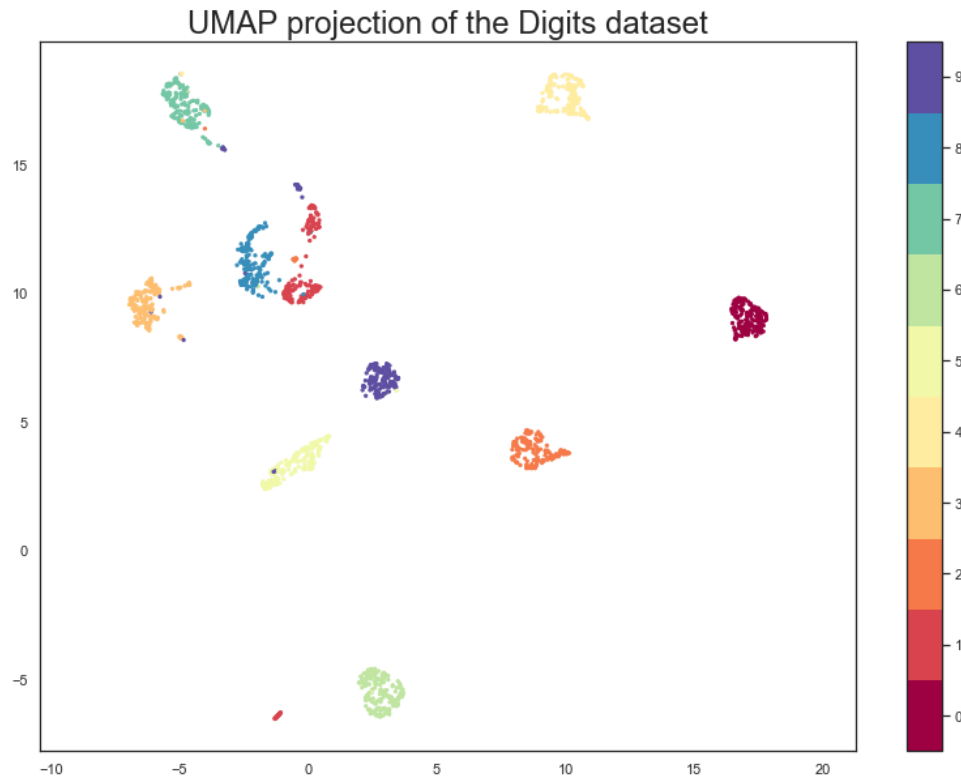
- Process to build a weighted graph
  - Opacity of line represents strength of a relationship
- Nodes “push” and “pull” each other based on size of weights



Long version: [https://umap-learn.readthedocs.io/en/latest/how\\_umap\\_works.html](https://umap-learn.readthedocs.io/en/latest/how_umap_works.html)

# UMAP

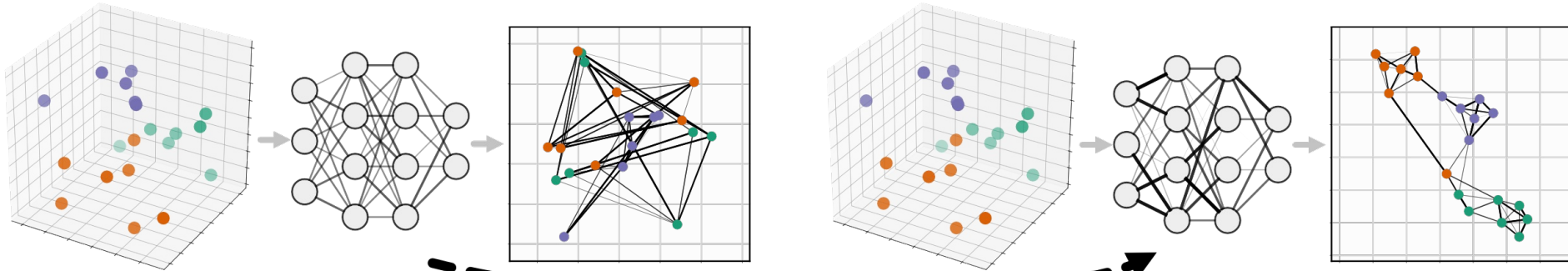
- Uses an approximation of these push/pull forces to give a **differentiable objective function**: optimise using gradient descent (fast/easy)



Long version: [https://umap-learn.readthedocs.io/en/latest/how\\_umap\\_works.html](https://umap-learn.readthedocs.io/en/latest/how_umap_works.html)

# Extensions to UMAP

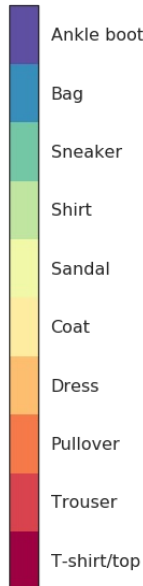
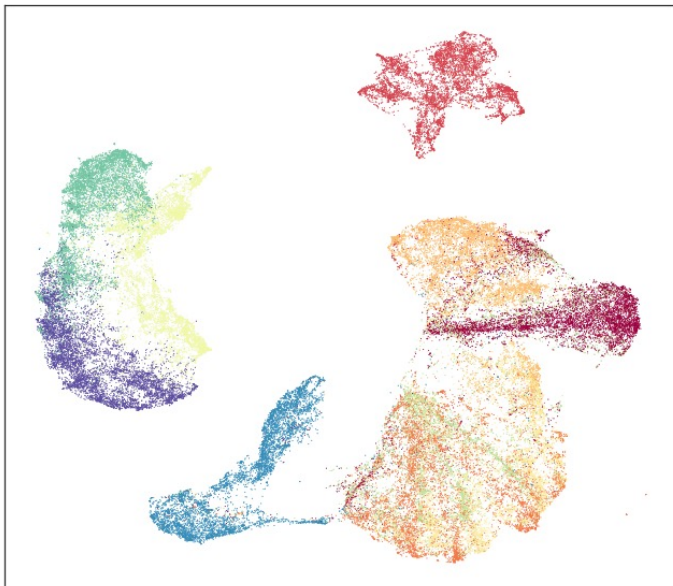
- **Parametric UMAP**: trains a NN to create the embedding



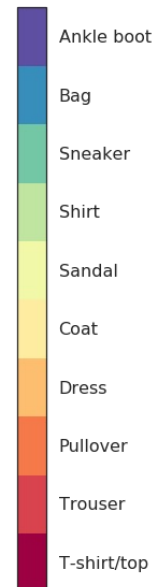
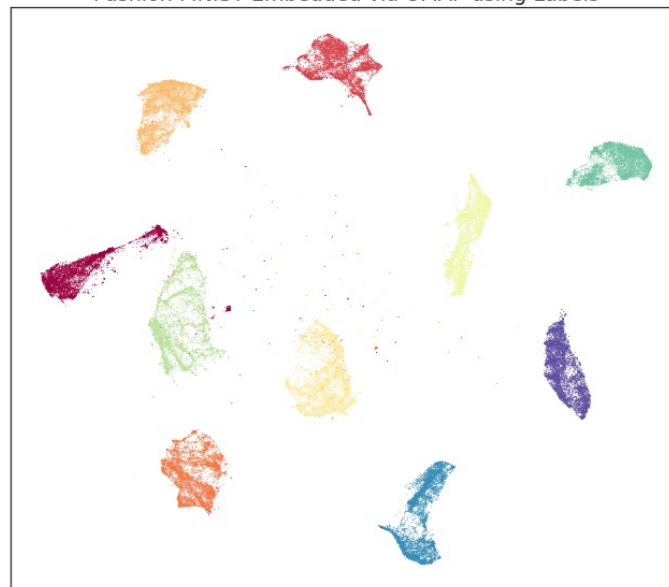
Learn a set of neural network weights that preserves the structure of the graph

- **(Semi-)Supervised UMAP**: combine the two “spaces”

Fashion MNIST Embedded via UMAP



Fashion MNIST Embedded via UMAP using Labels

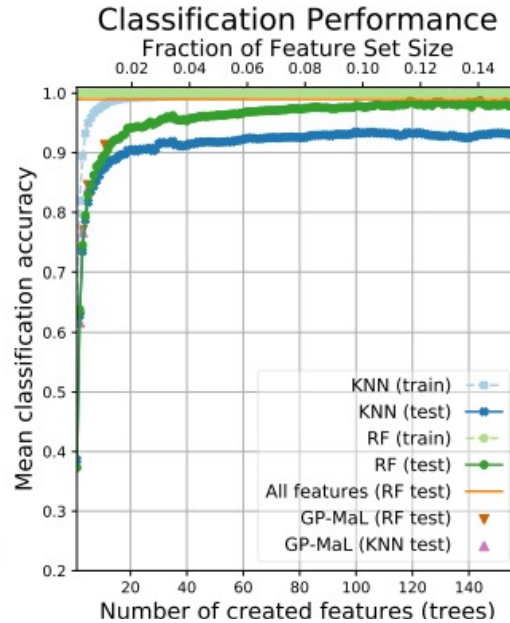
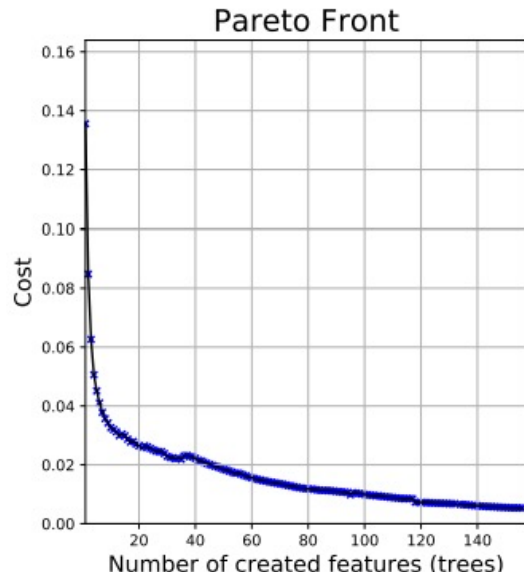


# Limitations of UMAP (and t-SNE)?

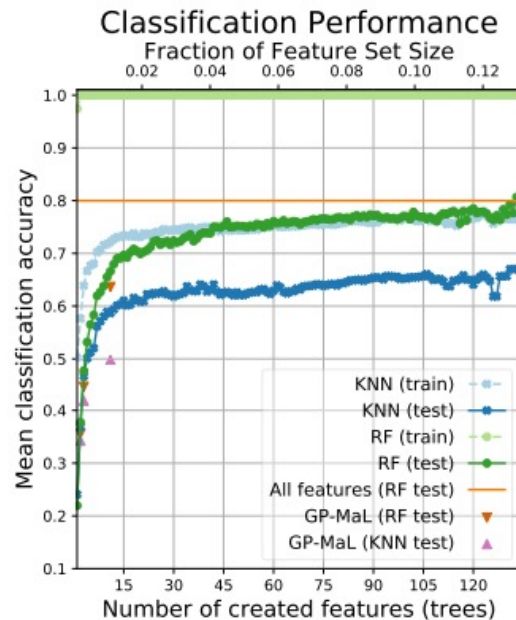
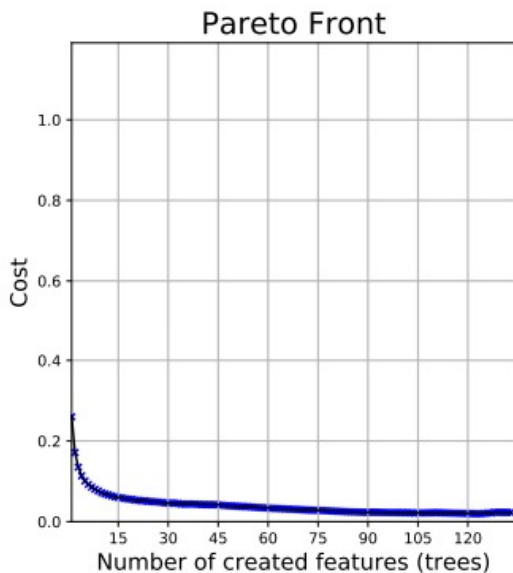
- Both t-SNE and UMAP *simplified/approximated* in order to make a differentiable objective function
  - What if better **non**-differentiable objective functions exist?
- Parametric t-SNE is a mapping – i.e. we have a concrete **functional model from  $D$  to  $d$** 
  - ...but is a 3-layer 100-neuron fully-connected NN at all interpretable?
  - I argue NO!
- Using EC/Genetic Programming to find simpler functional models/mappings for Manifold Learning.



# Manifold Learning: Embedding Quality vs Dimensionality

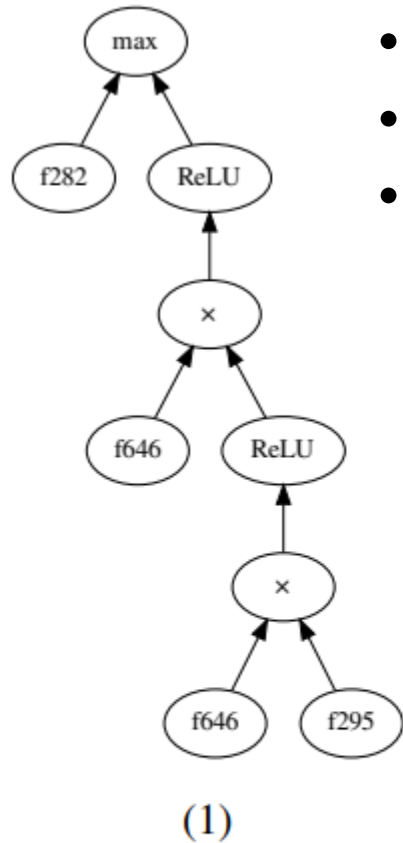


Diminishing returns –  
most data has low  
*intrinsic dimensionality*.

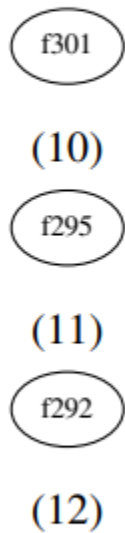
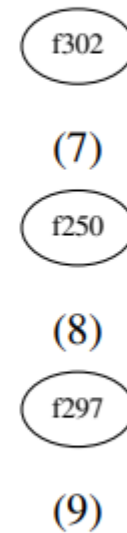
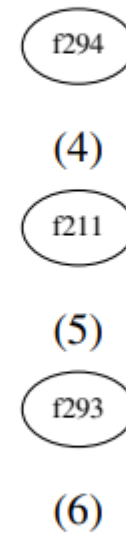
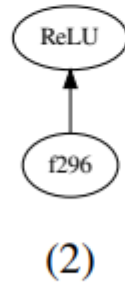


A. Lensen, M. Zhang, and B. Xue.  
“[Multi-Objective Genetic Programming for Manifold Learning: Balancing Quality and Dimensionality](#)” in *Genet Program Evolvable Mach* **21**, 399–431 (2020).  
<https://doi.org/10.1007/s10710-020-09375-4>

# Manifold Learning: Embedding Quality vs Dimensionality



- 649-dimensional MFEAT dataset;
- 12 evolved trees;
- 95% test accuracy (post-hoc).

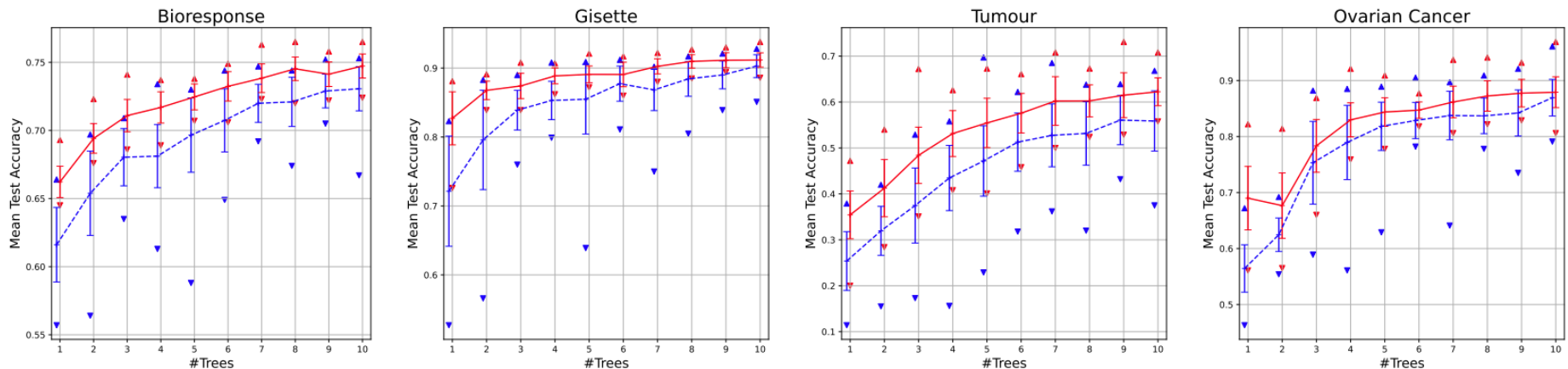


A. Lensen, M. Zhang, and B. Xue. [“Multi-Objective Genetic Programming for Manifold Learning: Balancing Quality and Dimensionality”](#) in *Genet Program Evolvable Mach* **21**, 399–431 (2020).  
<https://doi.org/10.1007/s10710-020-09375-4>

# Manifold Learning: Preserving Local Topology

A. Lensen, M. Zhang, and B. Xue. “[Genetic Programming for Manifold Learning: Preserving Local Topology](#)” in *IEEE Trans. Evolutionary Computation* (Early Access)  
DOI: [10.1109/TEVC.2021.3106672](#)

- There is an inherent trade-off between preserving *global* and *local topology*
- In many tasks, local topology preservation is more important
  - E.g. image segmentation, semi-supervised learning, ...
- Prioritising local topology preservation can retain more crucial structure



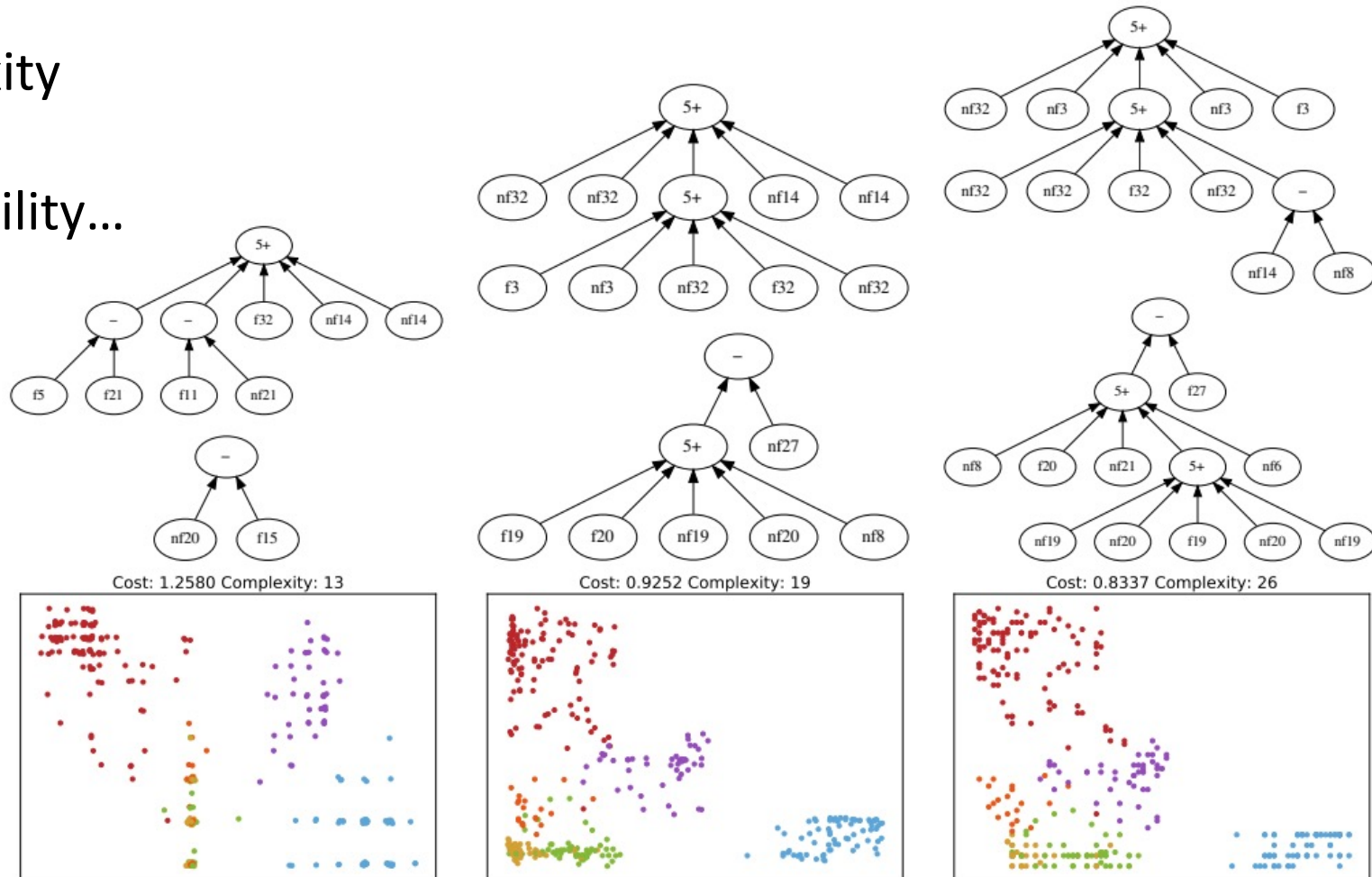


# *Explainable* Unsupervised Learning

What do these visualisations actually *mean*?

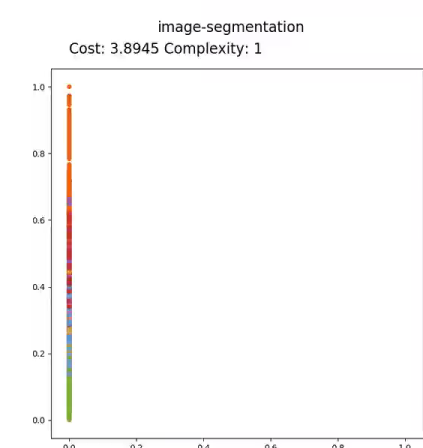
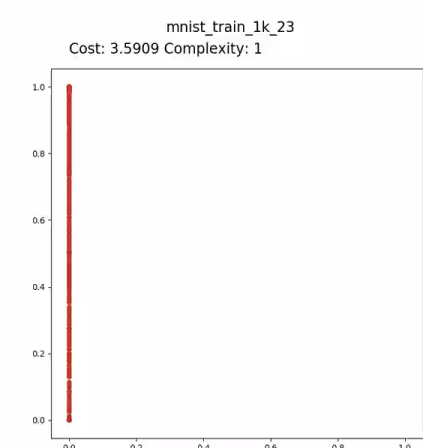
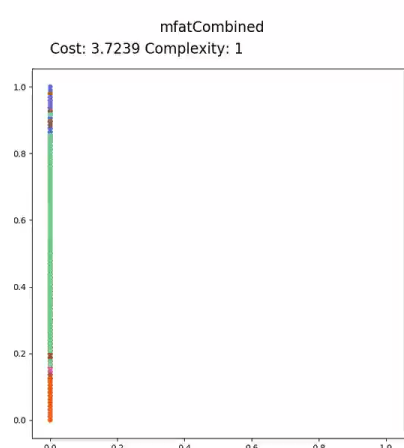
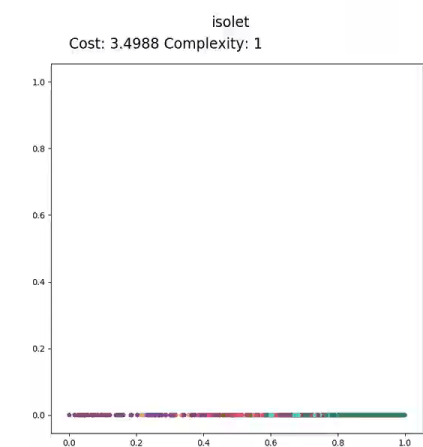
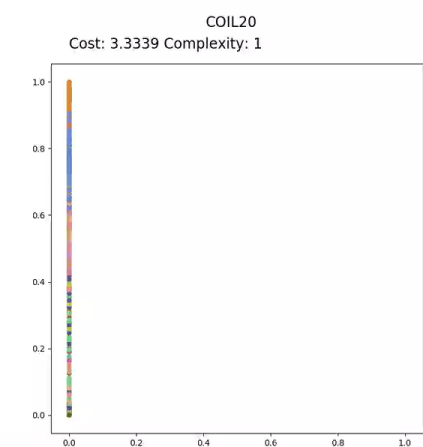
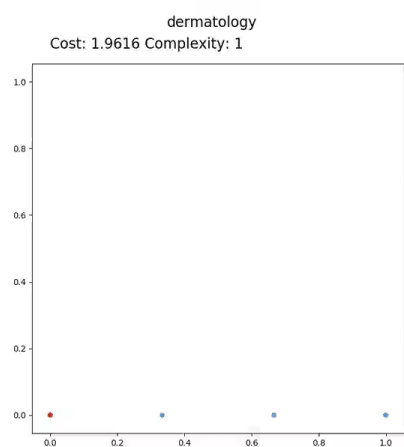
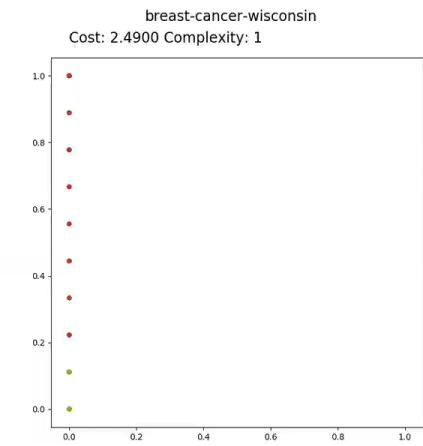
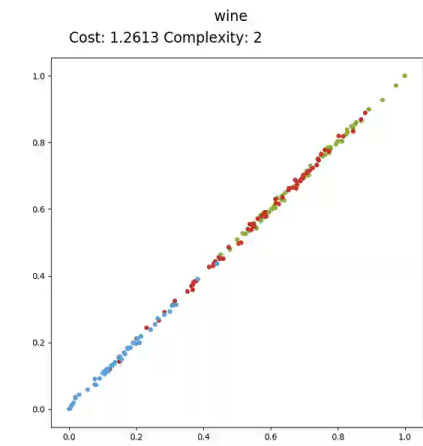
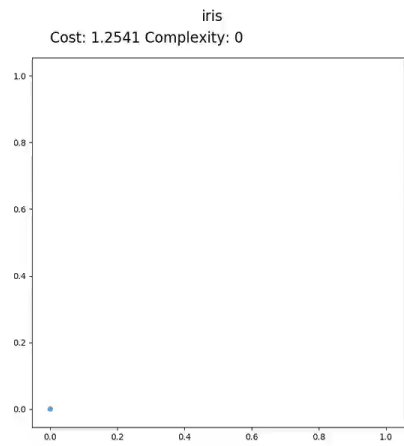
2D Manifold Learning  $\Leftrightarrow$  Visualisation?

Complexity  
VS  
Interpretability...



A. Lensen, B. Xue  
and M. Zhang,  
"[Genetic Programming for Evolving a Front of Interpretable Models for Data Visualisation](#)"

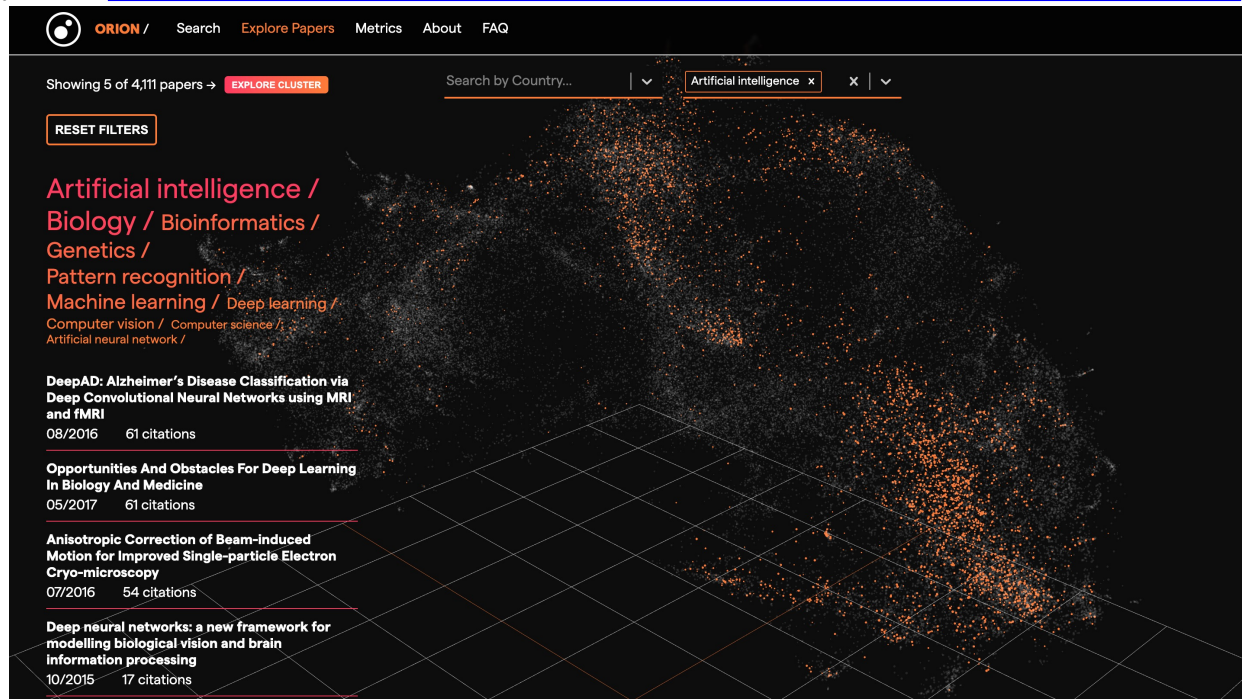
in *IEEE Transactions on Cybernetics*, doi:  
10.1109/TCYB.2020.2970198.



# Cool uses of UMAP

- Modelling 3D animals (wireframes) in [2D](#)
- Compare t-SNE vs UMAP vs PCA on [big datasets](#)
- [PixPlot](#): Embeds >27,000 historical photographs (2,048px) in 2D
- [Orion Search](#): Embedding of academic paper abstracts

(From [https://umap-learn.readthedocs.io/en/latest/interactive\\_viz.html](https://umap-learn.readthedocs.io/en/latest/interactive_viz.html))



# Demo Time

[https://colab.research.google.com/drive/1rF\\_gFIU7s5DGT3rHsAhP61EIDYYJMAYS?usp=sharing](https://colab.research.google.com/drive/1rF_gFIU7s5DGT3rHsAhP61EIDYYJMAYS?usp=sharing)