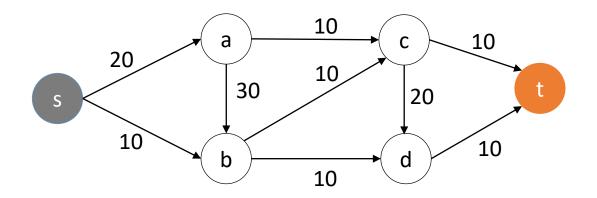
#### COMP261 Algorithms and Data Structures 2024 Tri 1

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# **Recap: Definition**

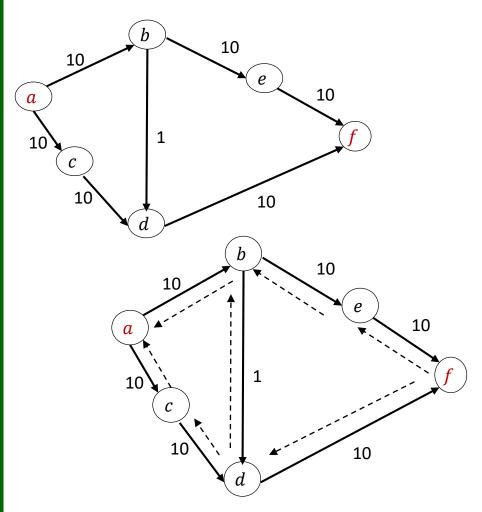
A flow network is a connected, directed graph G = (V, E) where:

- Each edge, e, has a non-negative, integer capacity  $c_e$ .
- One (or more) vertex is labelled as a source  $s \in V$ .
- One (or more) vertex is labelled as sink t  $\epsilon V$ .
- No edge enters the source and no edge leaves the sink.



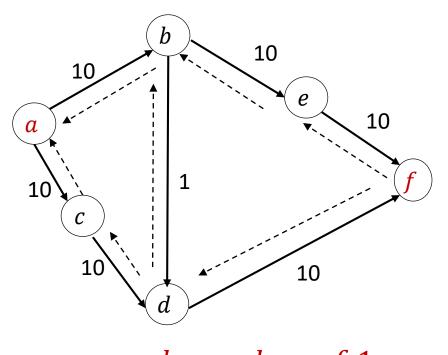
# Recap: Solving Maximum flow problem

How can we solve this problem ?



- Look for paths from source to destination and count them if they have capacities left
- Repeat until no paths from source to destination is found with capacities left
- 3. There could be a possibility that the paths we choose are not optimal have an option of reversing the decisions. For every edge in the original graph, we add an "imaginary" reverse edge

#### Solving Maximum flow problem



$$a \longrightarrow b \longrightarrow d \longrightarrow f 1$$
  

$$a \longrightarrow c \longrightarrow d \longrightarrow f 9$$
  

$$a \longrightarrow b \longrightarrow e \longrightarrow f 9$$
  

$$a \longrightarrow c \longrightarrow d \longrightarrow b \longrightarrow e \longrightarrow f 1$$

### Ford-Fulkerson method

It is generally called a method rather than an algorithm, as it encompasses several different implementations with different running times.

- Based on 2 important ideas:
  - Residual Graphs (includes reverse edges)
  - Augmentation paths (path in a residual graph)

### **Residual Graph**

Given a network G and a flow f, we construct a residual graph  $G_f$ , representing places where flow can still be added to f, including places where existing flow can be decreased.

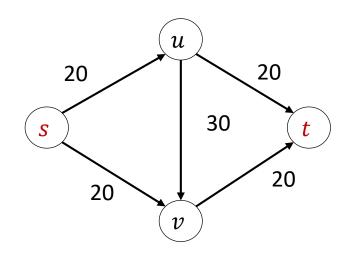
- • $G_f$  is defined as follows:
  - • $G_f$  contains same nodes a G.

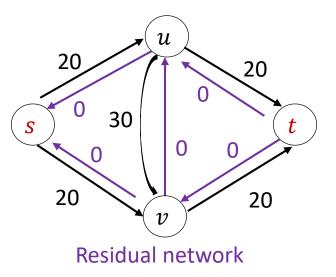
•Forward edges: for each edge e = (u, v) of G for which  $f_e < c_e$ , include an edge e' = (u, v) in  $G_f$  with capacity  $c_e - f_e$ 

•Backward edges (represent decreasing flow): for each edge e = (u, v) of G with  $f_e > 0$ , include an edge e' = (v, u) in  $G_f$  with capacity  $f_e$ 

### **Residual network**

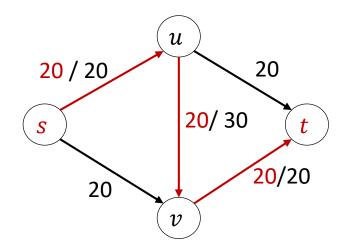
Initially flow is 0 for all edges.

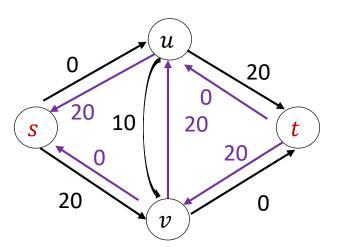




 $G_f$  contains same nodes a G. Forward edges: for each edge e = (u, v) of G for which  $f_e < c_e$ , include an edge e' = (u, v) in  $G_f$  with capacity  $c_e - f_e$ Backward edges: for each edge e = (u, v) of G with  $f_e > 0$ , include an edge e' = (v, u) in  $G_f$  with capacity  $f_e$ 

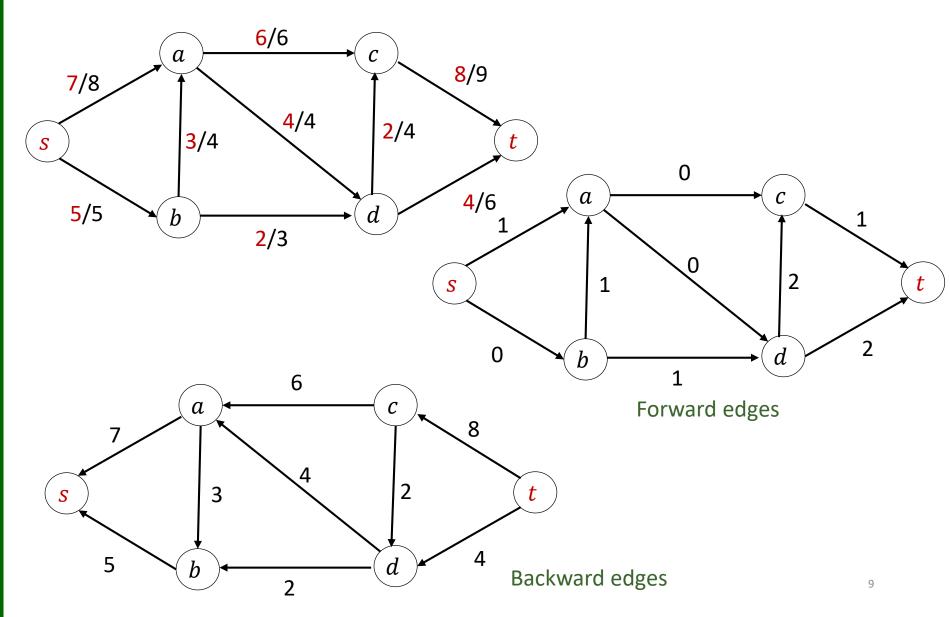
#### **Residual network**



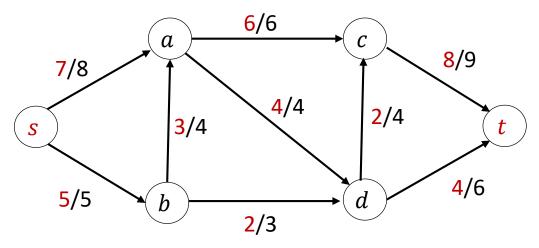


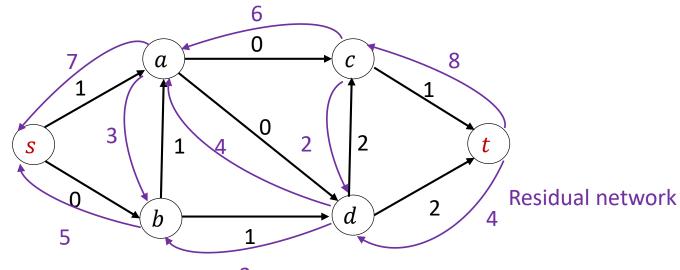
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#### Example



#### Example



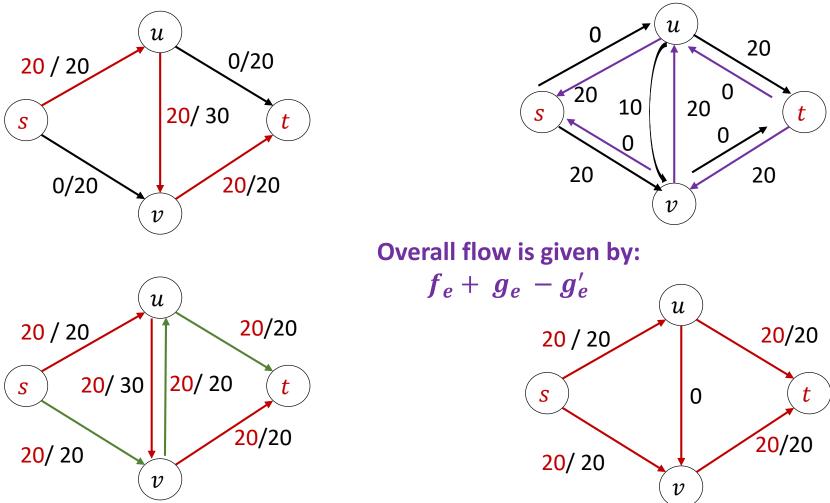


# Augmentation Path

- Augmentation path: Given a network G and a flow f. Augmentation path is any flow g on residual graph  $G_f$  from source s to destination t.
- Augmentation path *g* can be added to *f* to get a new flow on *G*.
  - $g_e$  (forward edge) adds to  $f_e$
  - $g'_e$  (backward edge) subtracts from  $f_e$  (equivalent of reversing our previous decision)

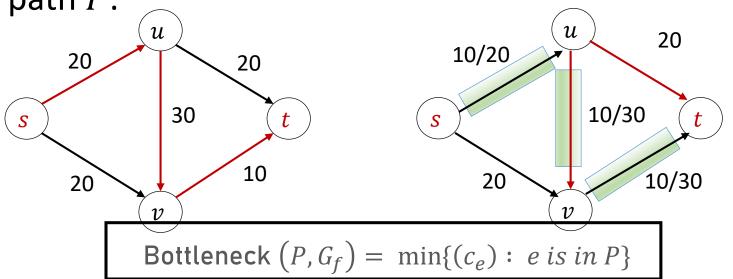
#### Example

Residual Graph



# **Augmenting Paths**

- How much flow can be added in each step?
- Bottleneck  $(P, G_f)$ : the smallest capacity in  $G_f$  on any edge of P. If bottleneck  $(P, G_f) > 0$  then we can increase the flow by sending bottleneck  $(P, G_f)$  along the path P.



# Ford-Fulkerson method

• Follows a greedy approach. Iteratively increase the value of flow.

```
FordFulkerson(G, s, t)
Let f_e = 0 for all edges (no flow anywhere)
Initialize Residual Graph RG // for every forward edge in the
original graph G add a reverse edge with a capacity 0
maxFlow = 0
   Repeat
       Find some P path from s to t in RG such that c_e > 0 for all
       edges in P
           if P exists
              pathFlow = Bottleneck (P, RG)
              maxFlow = maxFlow + pathFlow
              Output (P, pathflow) as an augmentation path
              Update RG
       Fndif
   Until the RG has no more augmentation paths.
   Output maxFlow
```

Note: Ford-Fulkerson does not state how to find augmentation paths.

# **Updating Residual Graph**

For each edge  $e = (u, v) \in P$ :  $f_{(u,v)} = f_{(u,v)} + pathFlow //add$  flow  $c_{(u,v)} = c_{(u,v)} - pathFlow //reduce$  capacity

 $c_{(v,u)} = c_{(v,u)} + pathFlow//increase capacity in reverse edge EndFor$ 

Edmonds-Karp algorithm is an implementation of the Ford-Fulkerson method that uses BFS for finding augmenting paths.

```
BFS(RG, s, t)
Define augPath as ArrayList of edges
q := queue()
q.push(s)
backpointer(v) = null for all v // backpointer data-structure to hold
                                  //edges that lead to the vertex
while !q.isEmpty()
   cur := q.pull()
   for each outedge e of cur in RG do
     if e.toCity! = s and backpointer(e.toCity) == null and e.cap \neq 0
          backpointer(e.tocity) := e
          if (backpointer(t)! = null) // found a path from s to t. Build it now from reverse
             pathEdge = backpointer(t)
             while(pathEdge! = null)
                  augPath.add(pathEdge)
                  pathEdge = backpointer(pathEdge.fromCity)
             endWhile
             Collections.reverse(augPath)
             return augPath
          endIF
          q.push(e.toCity)
     endIf
   endFor
endWhile
return null
```

#### Next Lecture

• Example – Edmonds-Karp algorithm