Fundamentals of Artificial Intelligence

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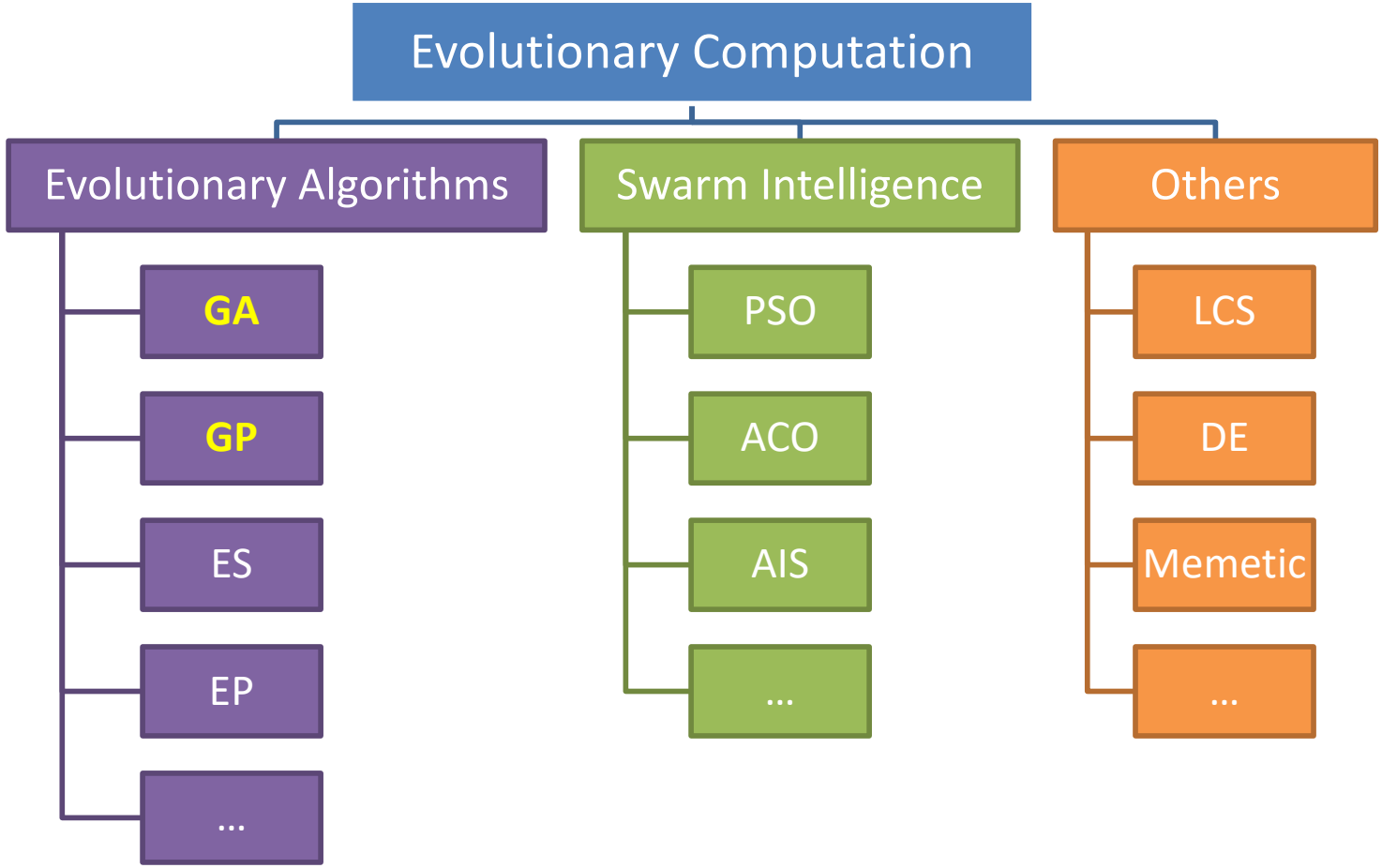
COMP307/AIML420

Evolutionary Computation 2:
Genetic Programming (GP)

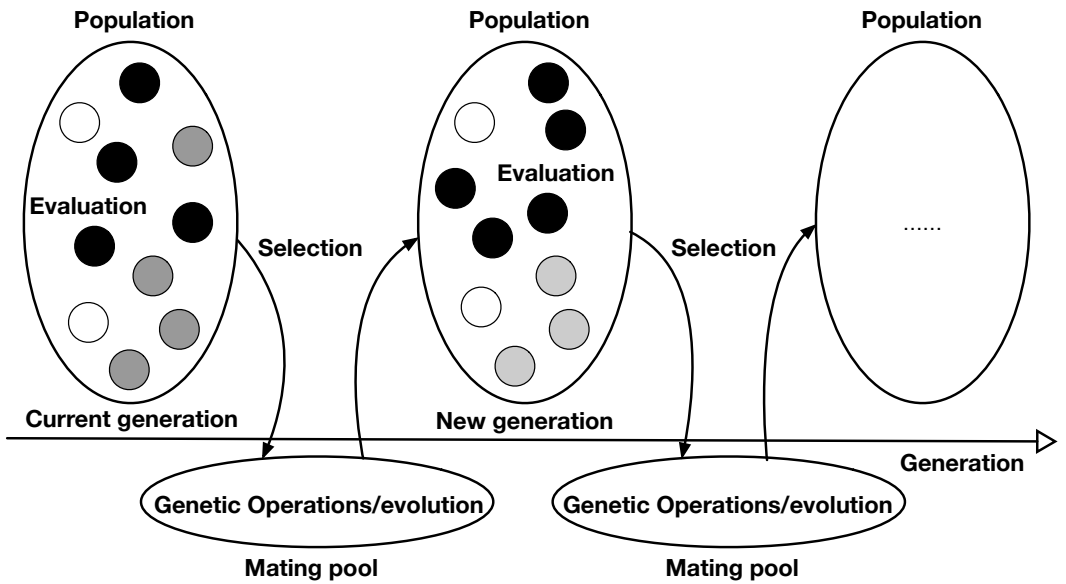
Review – Evolutionary Computation

- Includes nature-inspired techniques and population-based approaches
  - Evolutionary algorithms (natural evolution-inspired)
  - Swarm intelligence (more social-inspired)
  - Others …



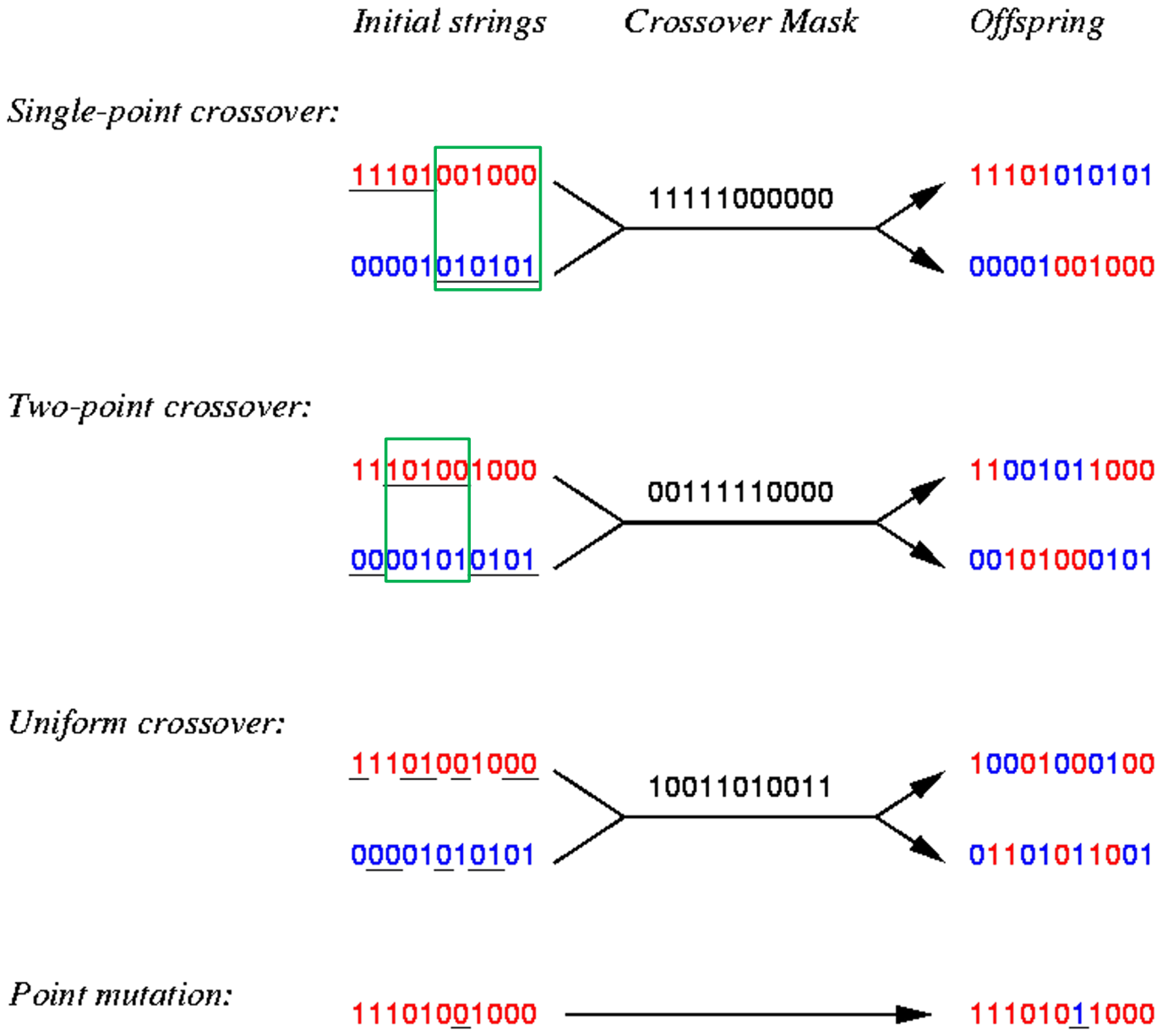
Review – Keys of Genetic Algorithm

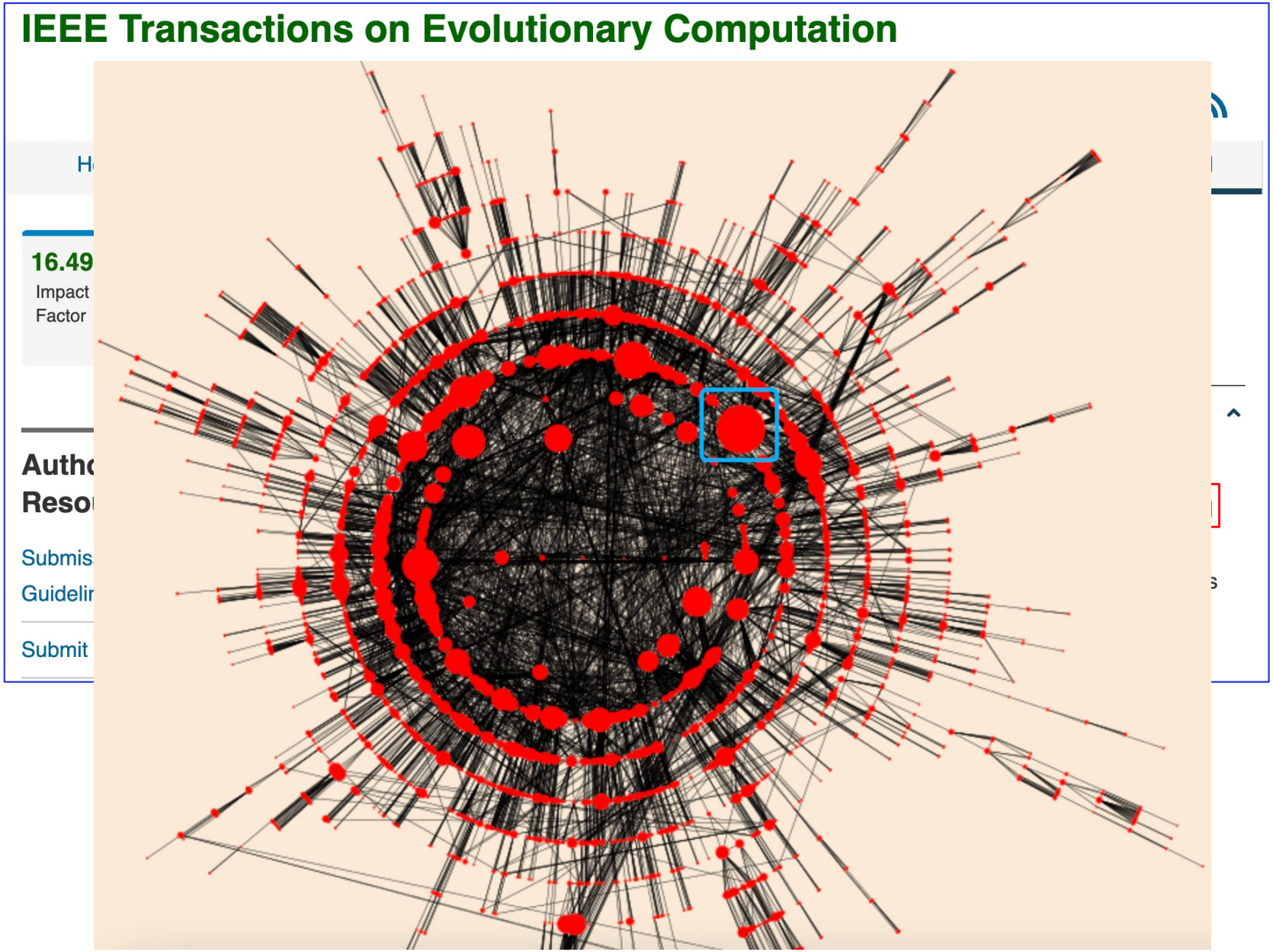
- Population based
- Evolution process, i.e., improve solutions generation by generation



- Representation
- Evaluation
- Parent selection
- Offspring generation (genetic operators)

Review – Genetic Operators





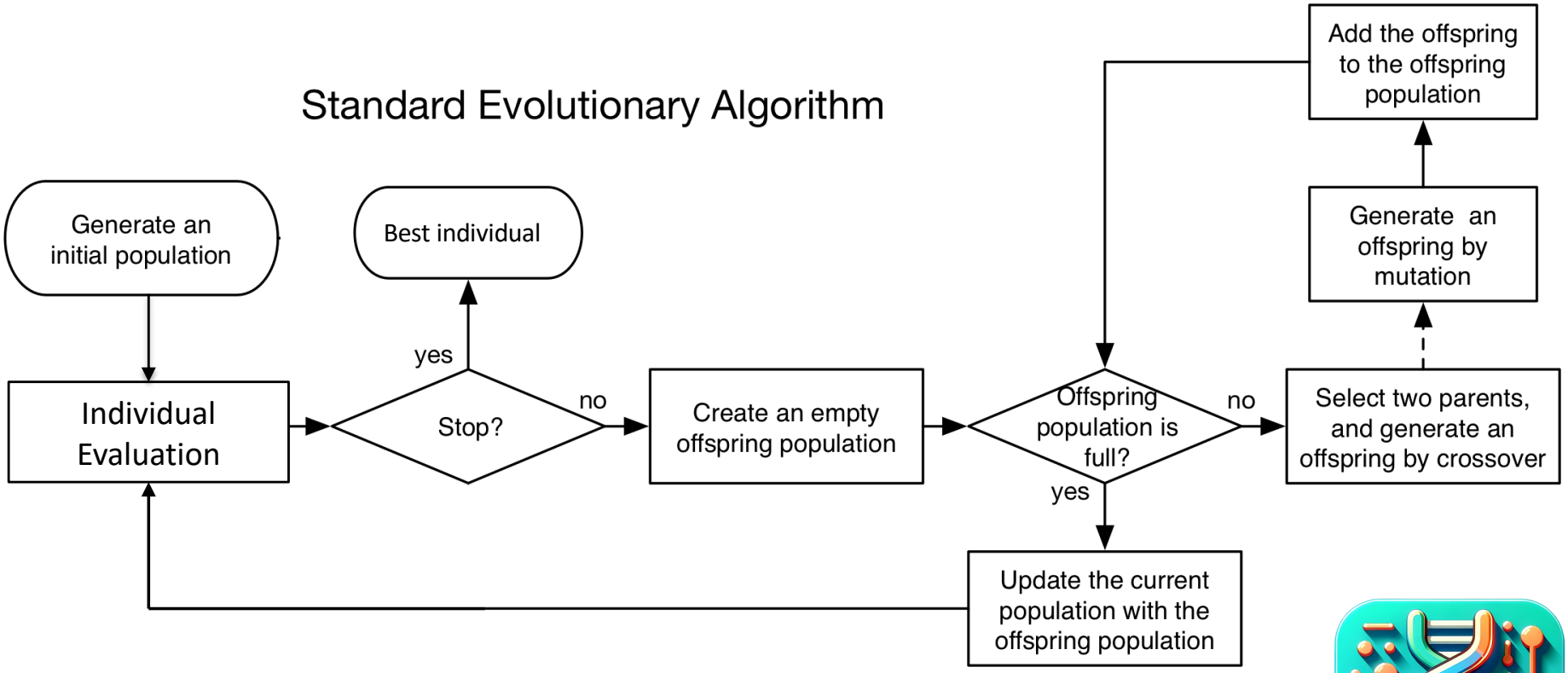
http://gpbib.cs.ucl.ac.uk/

Outline

- GP representation: Terminals and functions
- Program generation
- Evaluation: Fitness functions
- Parent selection
- Offspring generation: Genetic operators
- A basic GP algorithm
- Tackling a problem with GP

Genetic Programming

- GP follows the process of a standard evolutionary algorithm



Genetic Programming

- **Genetic programming (GP)** inherits properties from Evolutionary Algorithms (e.g., GAs) and automatic program learning
- Automatically learning a set of computer programs for a particular task is a dream of computer scientists

- The term GP originates from the notion that computer programs can be represented as a tree-structured genome

- GP uses a similar evolutionary process to the general evolutionary algorithms (e.g., GAs)
  - GA uses bit strings to represent solutions;
    GP uses tree-like structures that can represent computer programs
  - GA bit strings use a fixed length representation;
    GP trees can vary in length

LISP S-Expressions

- Form of a LISP function:
  (*FUNCTION-NAME ARG1 ARG2 ARG3, …*)

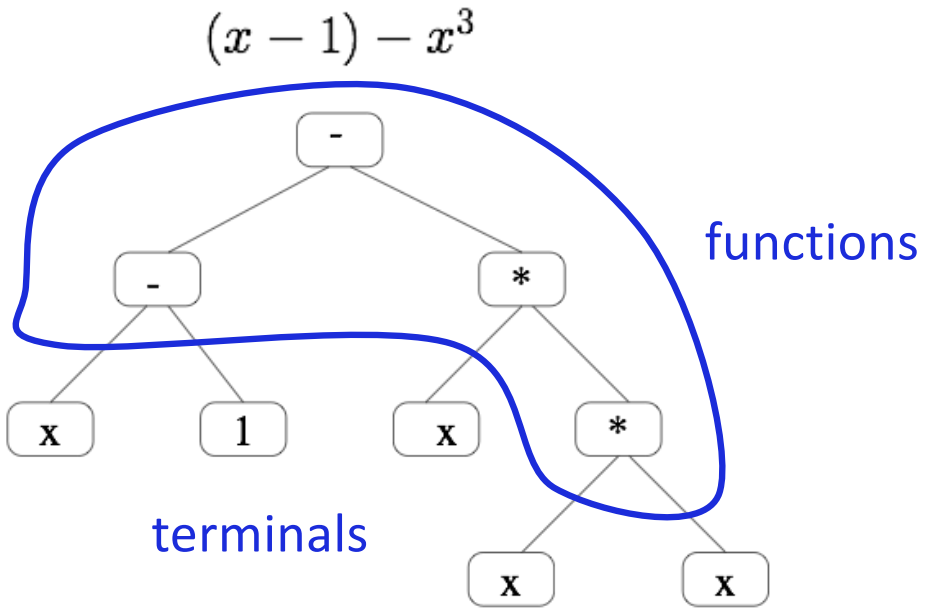
  The arguments are evaluated, the function is applied to the arguments and then the output returned

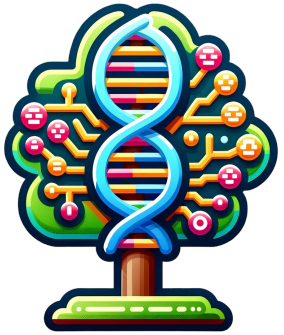
- (+ 1 2 3) evaluates to 6
- (+ (- 3 2) (* 2 4)) evaluates to (+ 1 8) which is 9
- (IF (> TIME 10) 3 4) evaluates to 3 if TIME is 11 or more,

  and to 4 if time is 10 or less
- If TIME=20, what is the value of (+ 1 2 (IF (> TIME 10) 3 4))?

Programs as Tree Structures

- Representation: Tree Structures
- Programs are constructed from a *terminal* set & *function* set
- Terminals and functions are also called primitives





GA vs GP: Representation

Genetic Algorithm

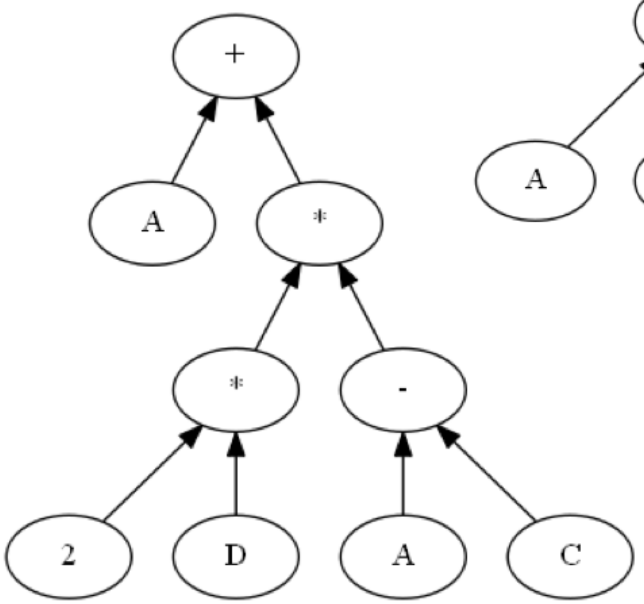
- Bit string representation
- Fixed in length
- Inflexible

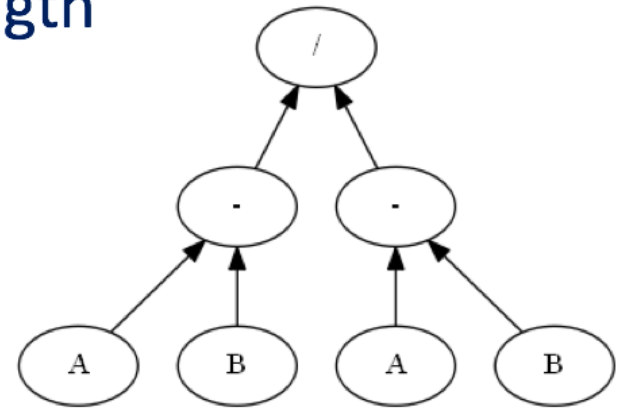
1	0	1	1	0	1	0	1	1	0

0	0	0	1	0	1	1	1	0	1

Genetic Programming

- Tree-like structure
- Vary in length
- Flexible





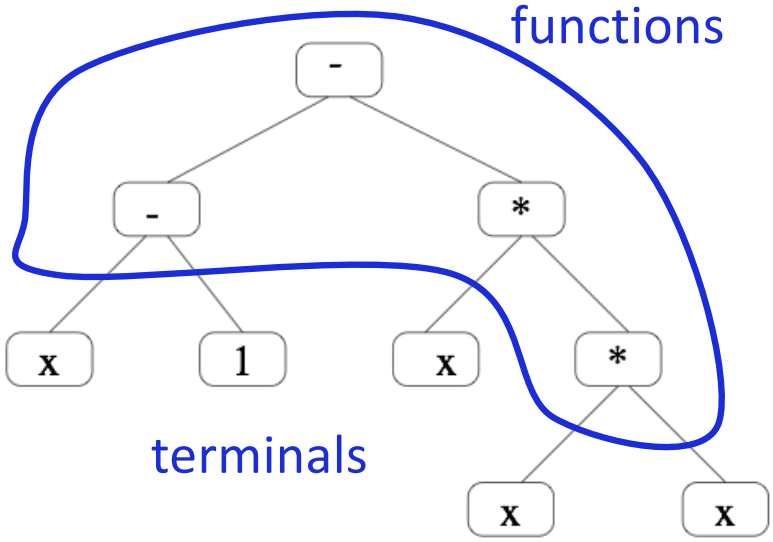
Terminal Set

- A terminal set consists of a set of terminals:
  - attributes/features
  - "Constants" (randomly generated, but don't change)

- Terminals have no arguments & form the leaves of the tree

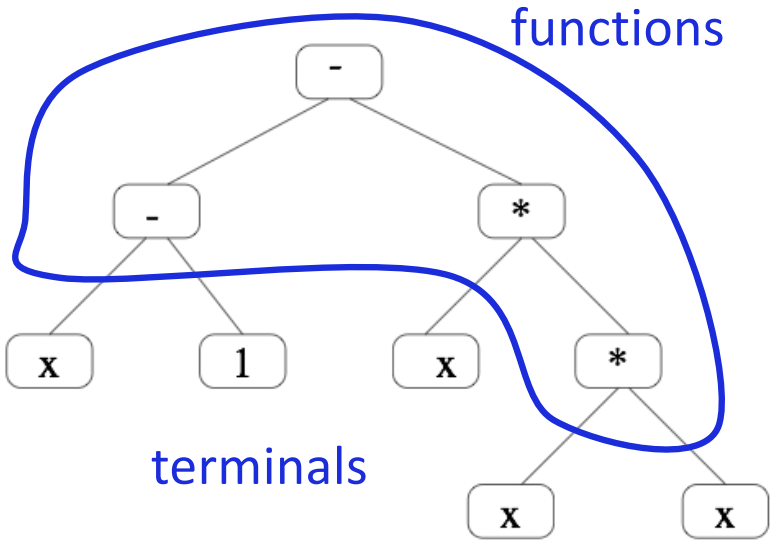
- Terminals represent the ***inputs*** of a GP tree/program, i.e. input from the environment (a specific task)

- Attributes or features of a problem domain are usually used as terminals



Function Set

- A function set consists of a set of functions or operators
- Functions form the root and the internal nodes of the tree representation of a program



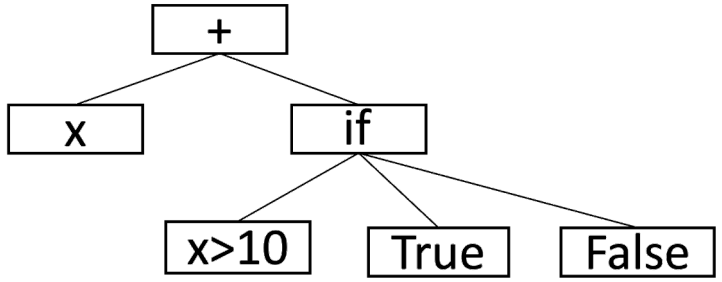
- Two kinds of functions: general functions, and domain-specific functions

- General functions:
  - Arithmetic functions: +, -, *, %.
  - Protected division (%): returns 0 (or 1) if denominator is 0
  - Other functions: sin, cos, exp, log, abs, ...

- Domain Specific functions: e.g., image processing operators

Sufficiency and Closure

- Selection of the functions and terminals is critical to success
- The terminal set and the function set should be selected to satisfy the requirements of *sufficiency* and *closure*
- Sufficiency: There must be some combination of terminals and function symbols that can solve the problem
- Closure: Any function can accept any input value returned by any function (and any terminal)
  - NB: “strongly-typed GP” violates this!

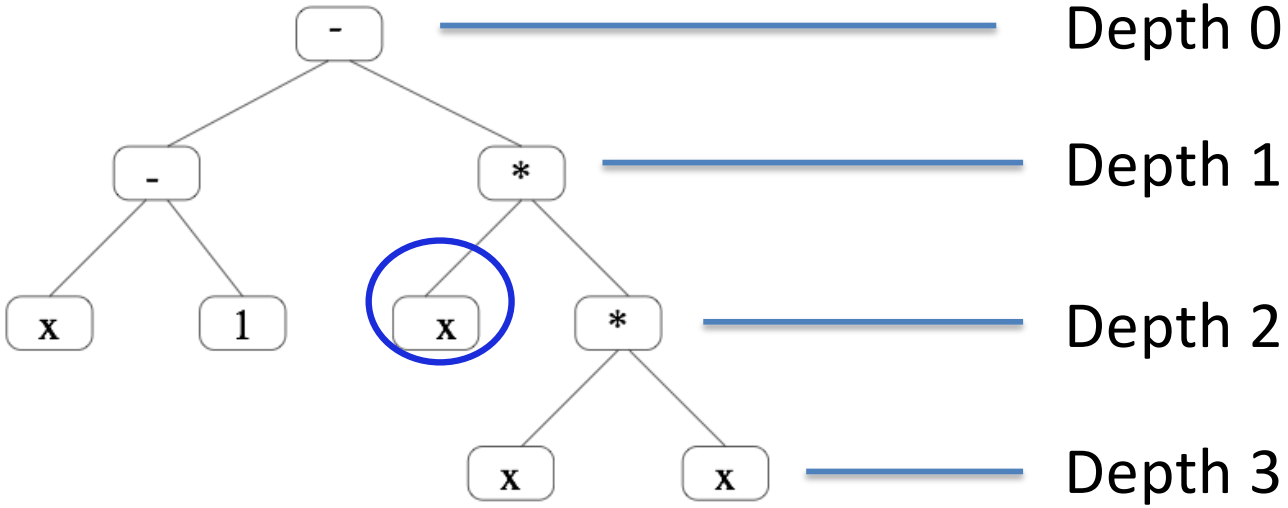


Program Generation

- For initializing a population, or performing

- Maximum program size: the maximum depth of a tree

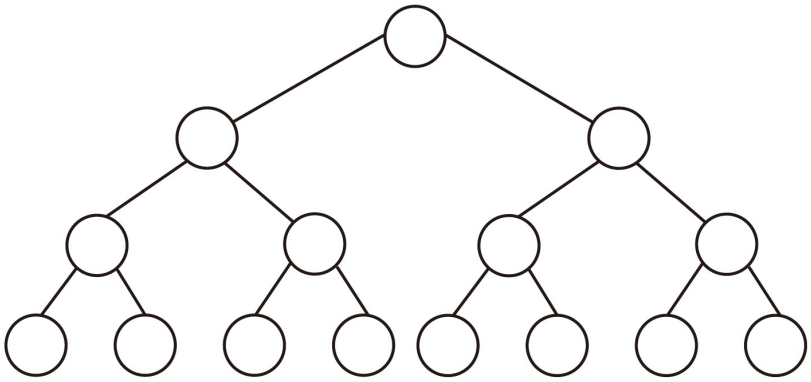
- Depth: The depth of a node is the minimum number of edges that must be traversed from the root of the tree to it



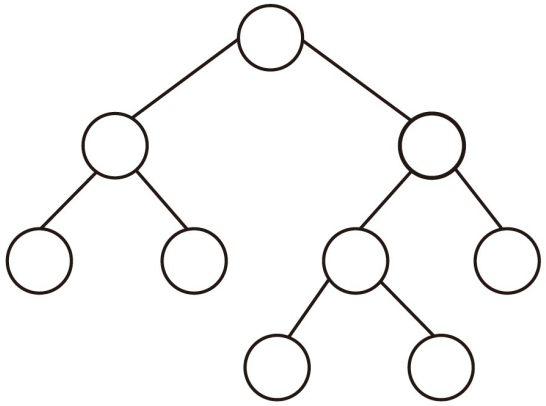
Program Generation

- There are several ways of generating programs: full, grow, and ramped half-and-half

- Full method:
  - Functions are selected as the nodes of the program tree until a given depth is reached
  - Then terminals are selected to form the leaf nodes
  - This ensures that full, entirely balanced trees are constructed



(a) *full*



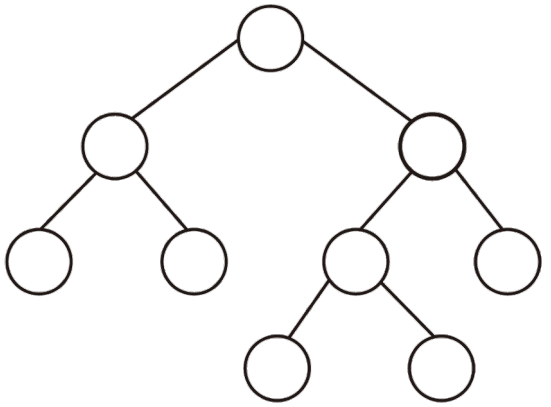
(b) *grow*

Program Generation

- Grow method:
  - Nodes are selected from **both functions and terminals**
  - If a terminal is selected, the branch with this terminal is terminated and we move on to the next non-terminal branch in the tree

- Ramped half-and-half method:
  - Both the full and grow methods are combined
  - Half of the population are created by using the grow method and the other half using the full method

- Ramped half-and-half is widely used in many GP systems
  - Good balance of the benefits of each!



(b) grow

Fitness Evaluation

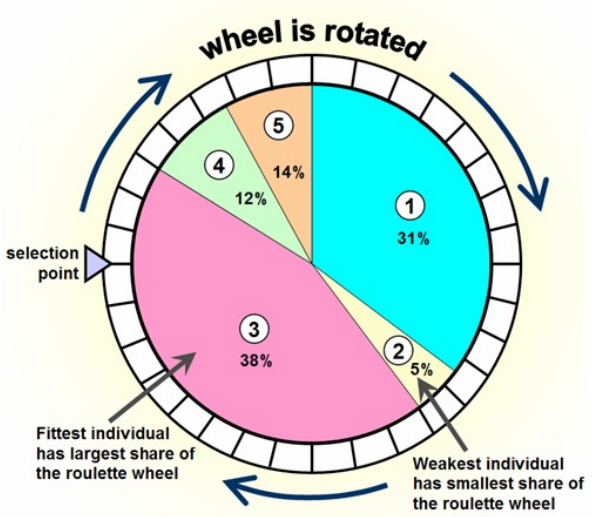
- The fitness of a program generated by the evolutionary process is evaluated according to the **fitness function**
- The fitness function should give graded and continuous feedback on how good a program is on the training set
- The fitness function plays a *very* important role in the evolutionary process and varies with the problem domain
- **Fitness cases**: instances used for fitness evaluation
  - Training cases: training instances used for learning
  - Test cases: test instances used for performance evaluation

Fitness Function Examples

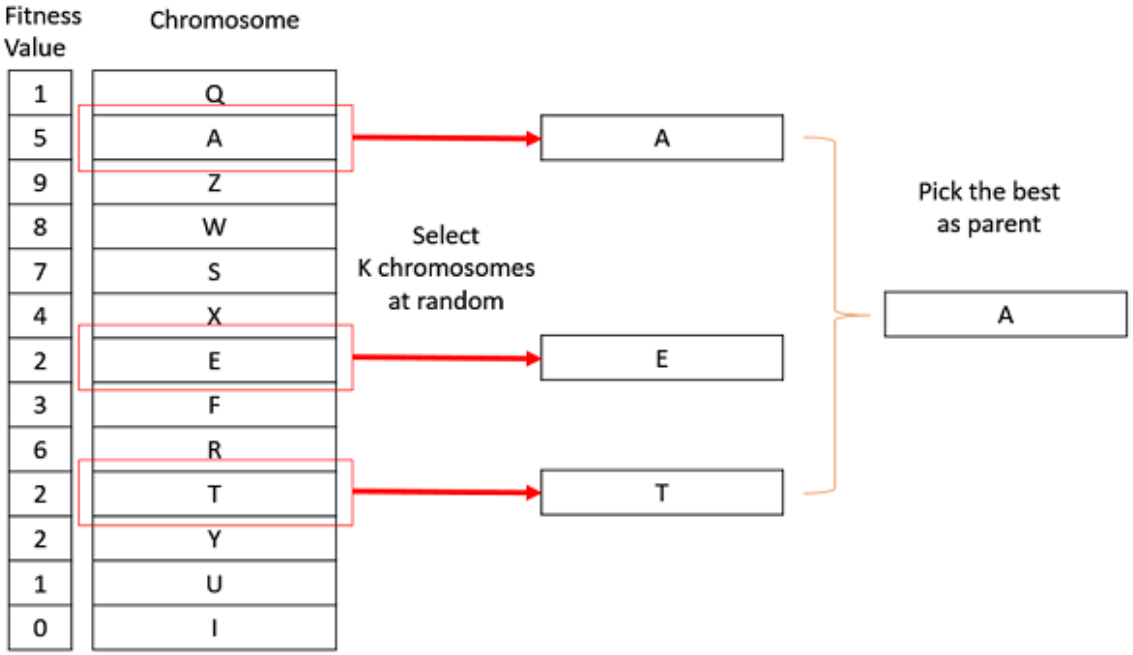
- Image matching: the number of matched pixels
- Robot learning obstacle avoidance: the number of walls hit for a robot
- Classification task: the number of correctly classified examples, error rate, or classification accuracy
- GP-controlled gambling agent: the amount of money won
- Artificial life application: the amount of food found and eaten

Parent Selection

- Roulette wheel selection (popularly used in GA)
  - The probability of being selected is proportional to the fitness
  - Assume fitness is maximized



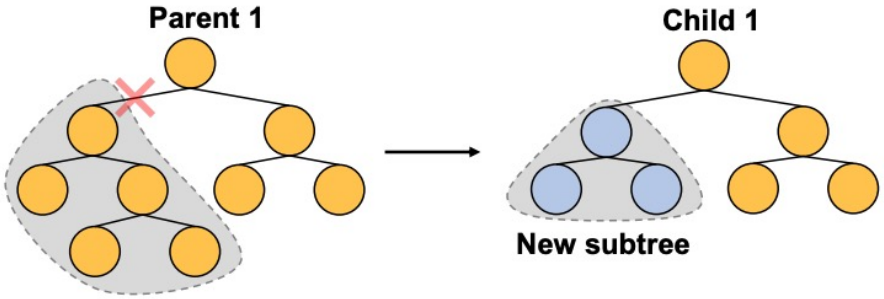
- K-tournament selection (popularly used in GP)
- Larger K, greedier?
- Small K, greedier?



Genetic Operators in GP

- Evolution proceeds by updating the initial population by the use of genetic operators
  - An initial population usually has very bad fitness
  - Three main operators in GP: reproduction, mutation, and crossover

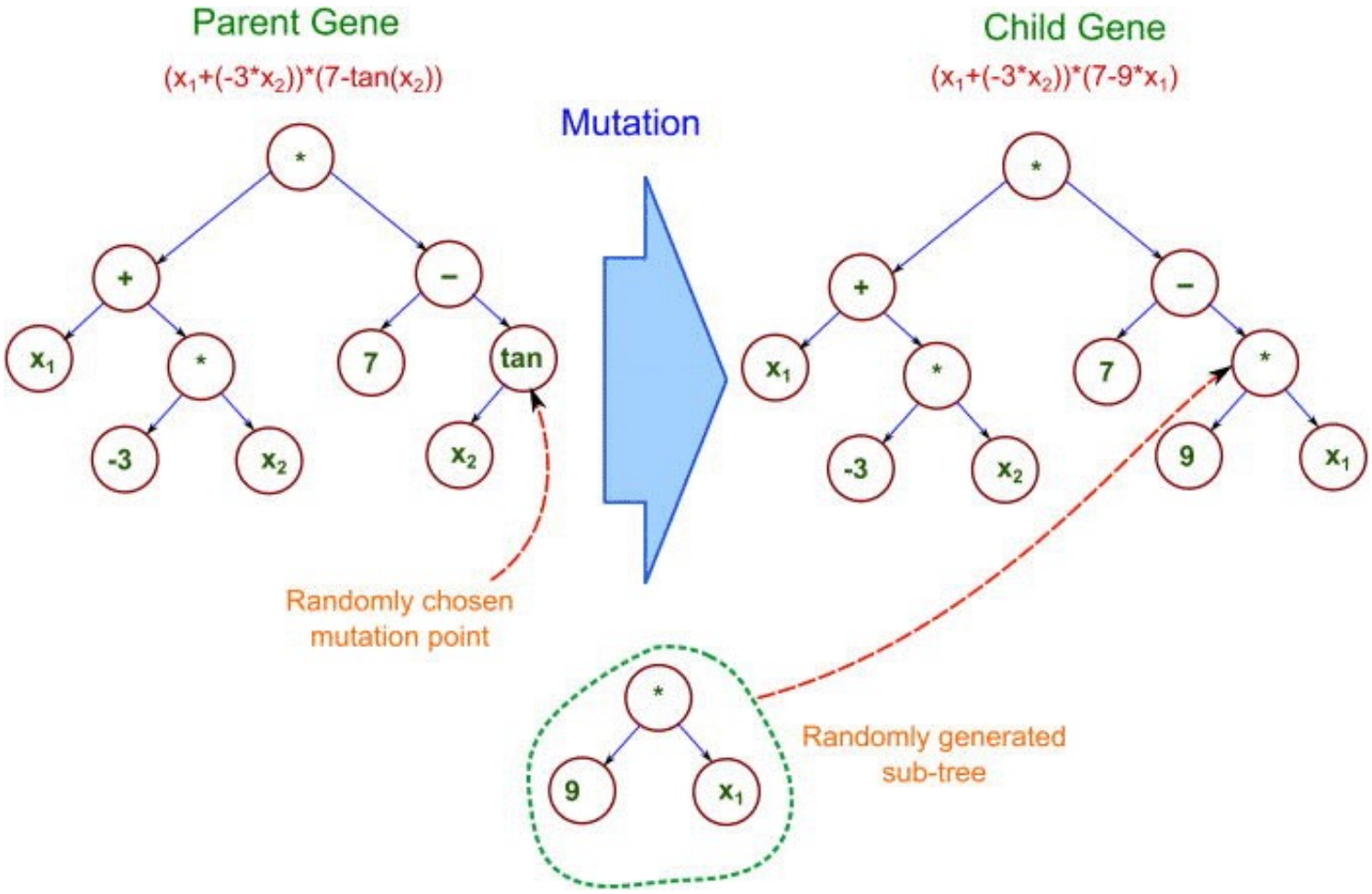
- Reproduction:
  - Simply copy a selected program to the new generation
  - Allow good programs to survive
  - Elitism: keep only the best one or several



Mutation

- Mutation:
  - Operate on a single selected program
  - Remove a random subtree of the program
  - Generate a new subtree in the same place

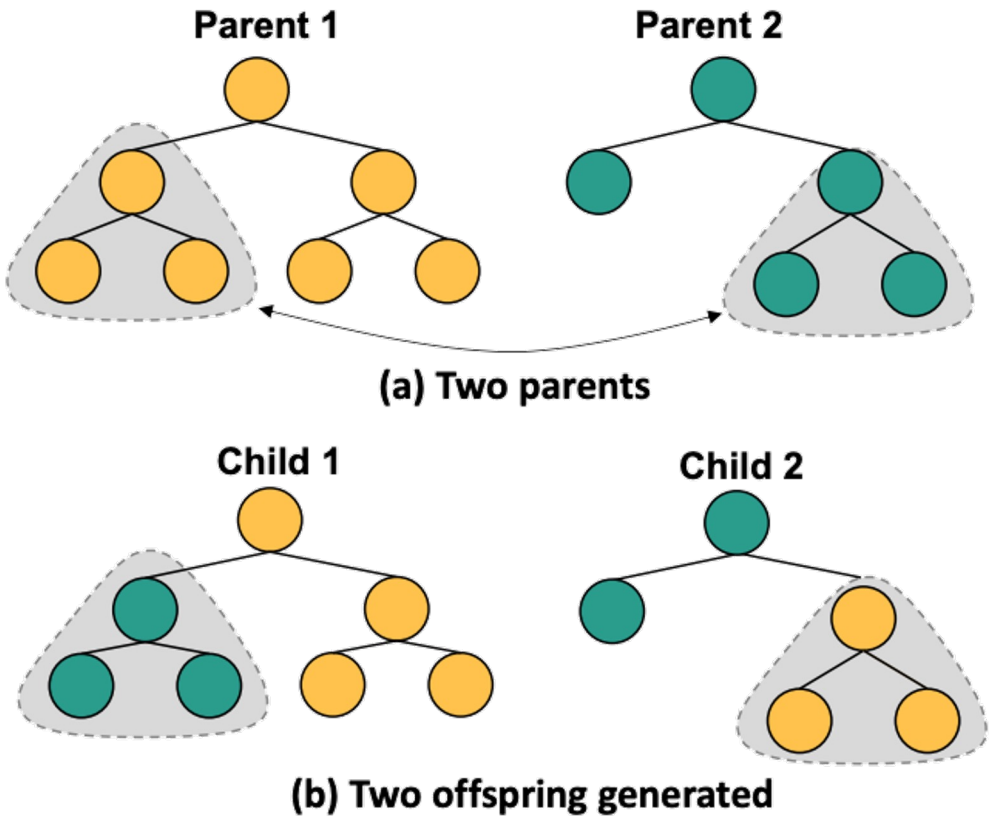
Mutation in GP



Crossover in GP

- Swap a subtree of one parent with a subtree of the other

- Put the two newly-formed programs into the next generation



Crossover

Crossover in GP

- Swap a subtree of one parent with a subtree of the other
- Put the two newly-formed programs into the next generation
- How is the tree depth used?

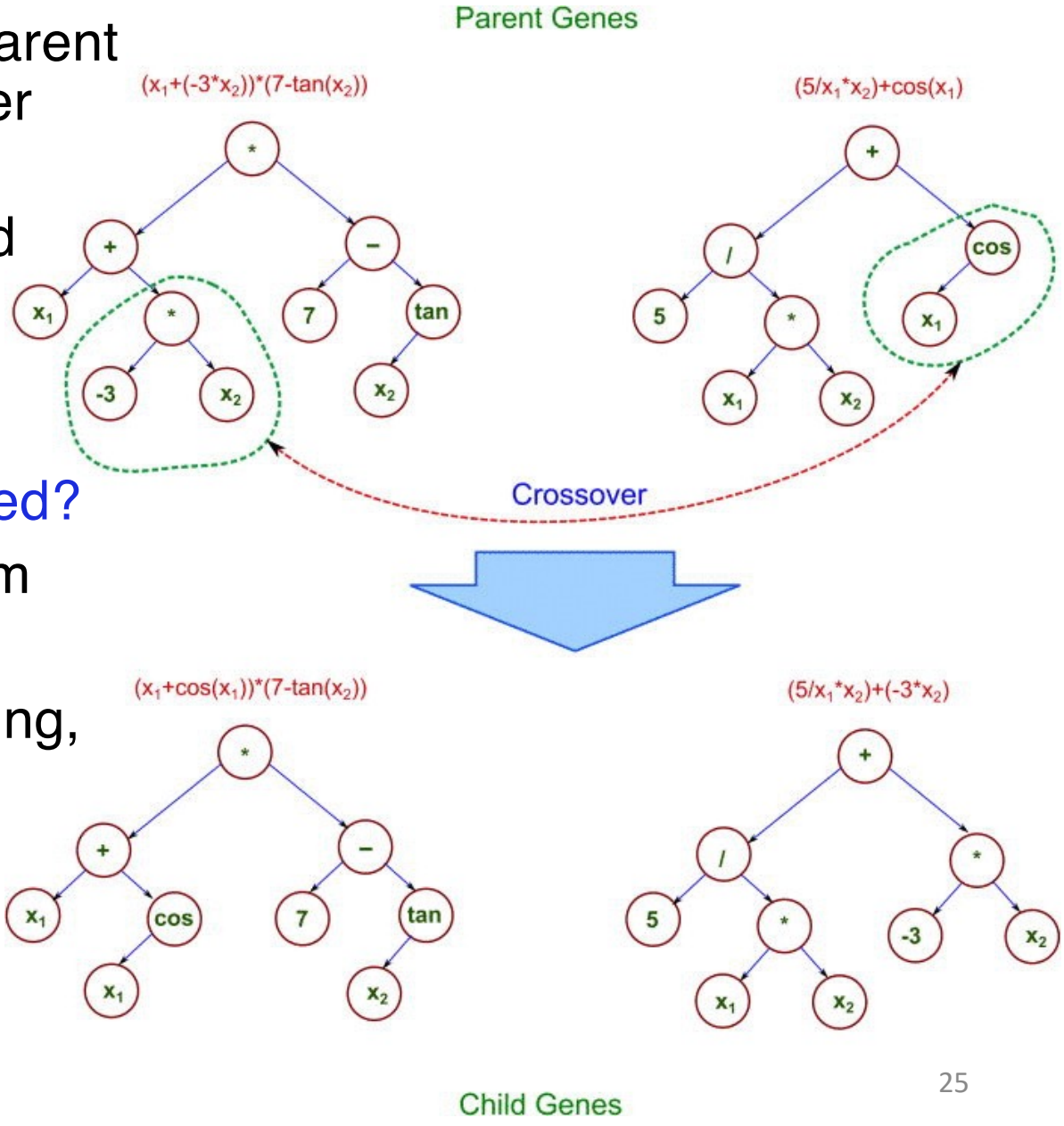
  After we get offspring from crossover/mutation, we check the depth of offspring,

  if depth(new) > depth,

  throw away;

  Otherwise,

  keep them;



A Basic GP algorithm

- Initialise the population

- Repeat until the stopping criteria is met:
  - Evaluate the fitness of each program in the current population
  - Create an empty new population
  - Repeat until the new population is full:
    - Select programs in the current generation (often *tournament selection*)
    - Apply genetic operators to the selected programs to generate offspring (*e.g., 80% crossover, 15% mutation, 5% reproduction*).
    - Insert the children programs into the new generation.

- Output the best individual program in the population.

Tackling a Problem with GP

- What terminals should be used in the program trees?
- What functions are needed to represent the program tree?
- What is the fitness function/measure?
- Parameters values for controlling the evolutionary process:

  e.g. what population size, tree depth and tournament size?
- When to terminate a run?
- Which genetic operators should be used, and how

  frequently should they be applied?

Popularly used GP libraries

- DEAP in Python
  https://github.com/DEAP/deap

- ECJ in Java
  https://cs.gmu.edu/~eclab/projects/ecj/
  can check more details at **src/ec/app/tutorial**

Summary

- Overview of EC (GA) process
- GP basics: representation, terminals, functions, fitness, genetic operators, selection
- GAs vs GP
- Basic GP algorithm
- Next lecture: GP regression and classification