## COMP307/AIML420 INTRODUCTION TO ARTIFICIAL INTELLIGENCE



**Reasoning under uncertainty: Probability Basics** 

## Outline

- 1. Introduction
- 2. Probability basics
- 3. Product Rule
- 4. Sum Rule
- 5. Normalisation Rule
- 6. Independence

## **Reasoning under uncertainty**

- **Medical diagnosis**: Medical Doctors often need to make diagnoses based on **incomplete information** and **uncertain test** results.
- Weather forecasting: Meteorologists use complex models to provide probabilities of different weather outcomes
- Financial decision making: Investors often need to make decisions based on uncertain market conditions and future projections
  - The <u>quants</u> use lots of probability theory
- **Machine learning:** Most new learning algorithms are based on probability theory. Many directly output probabilities.

# Uncertainty

- In most practical problems, there are **unknown** or **not precisely known** things
- Classes of uncertainty (in practice not so important)
  - Aleatoric (AKA statistical) uncertainty: inherent randomness or variability:
    - Quantum mechanics
    - Natural disasters
    - Geopolitical uncertainty
  - Epistemic uncertainty: results from a lack of knowledge:
    - Model parameters that are not precisely known
    - Finite-element computation of a tsunami
- Uncertainty plays a fundamental role in Al
- **Probability theory**: a mathematical framework for quantifying uncertainty

# **Belief about Propositions\* / Events**

- Instead of evaluating the truth or falsehood of a proposition, reason about the degree of belief that a proposition or event is true or false
- For each primitive proposition or event, attach a degree of belief to the sentence

- Probability theory provides a formal framework for manipulating these degrees of belief
- Example propositions / events
  - It will rain tomorrow
  - One possible prediction from a classification model ("it is a crow")

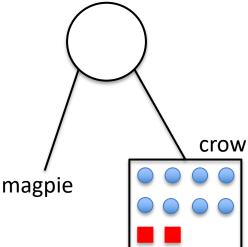
\* Proposition: a statement that expresses a fact or a judgment that is either true or false.

# **Belief about Propositions\* / Events**

- Instead of evaluating the truth or falsehood of a proposition, reason about the degree of belief that a proposition or event is true or false
- To each primitive proposition or event, attach a **degree of belief**

- Probability theory provides a formal framework for manipulating these degrees of belief
- Example propositions / events
  - It will rain tomorrow
  - A prediction choice from a classification model

"it is a crow"



\* **Proposition:** a statement that expresses a fact or a judgment that is either true or false.

## **Probability**

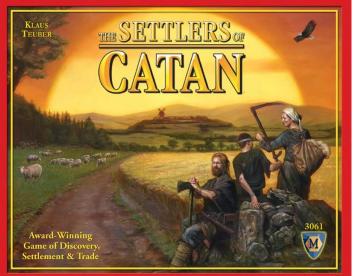
- Given a **proposition** *A*, where *A* is either true or false (binary)
  - The probability that A is true is written as P(A)
  - $\quad 0 \le P(A) \le 1$
- Sample space: set of experiment outcomes
- **Event**: set of one or more experiment outcomes
- **Random variable (RV)**: formally a function mapping outcomes to numerical values
- Forms of **propositions**:
  - **Event** (happens) one of the corresponding set of experiment outcomes happens
  - random variable = specific numerical value
    - Probability that proposition X = x is true is written as P(X = x), and sometimes as  $p_X(x)$
- Example for weather:
  - **Sample space**: {*rainy*, *sunny*, *cloudy*, *other*}
  - Events/Propositions: {rainy}, {rainy or cloudy}, {rainy or cloudy or other}
  - **Random variable** *X*: rainy  $\rightarrow$  1, sunny  $\rightarrow$  2, cloudy  $\rightarrow$  3, other  $\rightarrow$  4
  - **Random variable** *Y*: rainy  $\rightarrow$  1, sunny  $\rightarrow$  2, cloudy  $\rightarrow$  1, other  $\rightarrow$  3
  - P(sunny or cloudy) = 0.5: probability weather will be sunny or cloudy is 50%.
- What is the sample space of the outcome of a die?
  - Here we can use random variable = experiment outcome (RV is identity map)
  - Example proposition: random variable = 3 (the RV takes the value 3, X = 3)

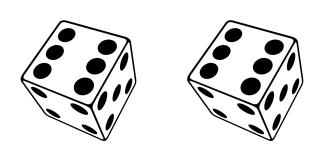


# **Probability**

- Notation
  - **AND**:  $A \cap B$ . The probability that **both** A and B are true:  $P(A \cap B)$ 
    - Sometimes written as  $A \wedge B$
  - **OR**:  $A \cup B$ . The probability that either A or B is true:  $P(A \cup B)$ 
    - Sometimes written as  $A \lor B$
  - NOT:  $\neg A$ . The probability that *A* is false ( $\neg A$  is true):  $P(\neg A)$
- Axioms of probability theory (Kolmogorov)
  - $P(A) \geq 0$
  - $-\sum_{A\in\Omega} P(A) = 1$ , where  $\Omega$  is the sample space
  - $P(A \cup B \cup C \cdots) = P(A) + P(B) + P(C) + \cdots$ , for mutually exclusive events  $A, B, C, \cdots$

#### Example: Catan

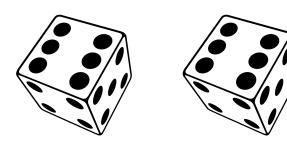






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• If we roll two fair dice, what is the probability that the sum of their outcomes is 11?



Dice1	Dice2	Sum
1	1	2
1	2	3
1	3	4
1	4	5
1	5	6
1	6	7
6	5	11
6	6	12

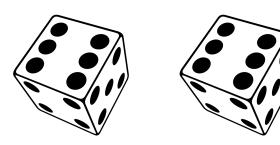
• If we roll two fair dice, what is the probability that the sum of their outcomes is 11?



• 36 possible outcomes in total

Dice1	Dice2	Sum
1	1	2
1	2	3
1	3	4
1	4	5
1	5	6
1	6	7
6	5	11
6	6	12

• If we roll two fair dice, what is the probability that the sum of their outcomes is 11?



- Sample space contains 36 pairs
- 36 possible outcomes
- 2 outcomes (5,6) and (6,5) give the total number of 11

Dice1	Dice2	Sum
1	1	2
1	2	3
1	3	4
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• If we roll two fair dice, what is the probability that the sum of their outcomes is 11?



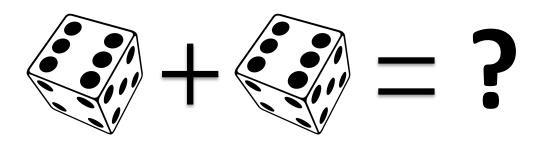


- Sample space contains 36 pairs
- 36 possible outcomes
- 2 outcomes (5,6) and (6,5) give the total number of 11
- P(Sum = 11) =

 $\begin{array}{l} P(die_{1} = 5, die_{2} = 6 \cup die_{1} = 6, die_{2} = 5) = \\ P(die_{1} = 5, die_{2} = 6) + P(die_{1} = 6, die_{2} = 5) = \\ 2/36 = 1/18 \end{array}$ 

Dice1	Dice2	Sum
1	1	2
1	2	3
1	3	4
1	4	5
1	5	6
1	6	7
6	5	11
6	6	12

• If we roll two fair dice, what is the most probable value obtained when we sum their outcomes?



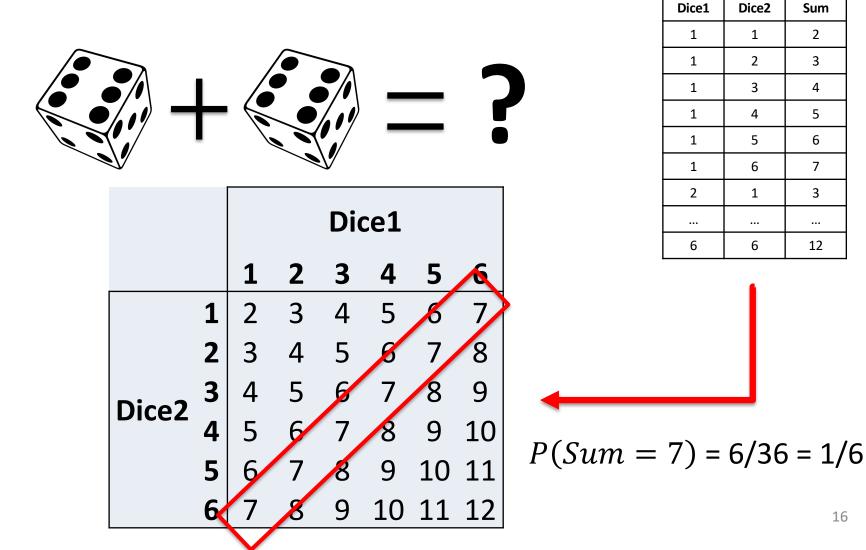
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• If we roll two fair dice, what is the most probable value obtained when we sum their outcomes?

-	┠							
				Dio	ce1			
		1	2	3	4	5	6	
	1	2	3	4	5	6	7	
	2	3	4	5	6	7	8	
Dice2	3	4	5	6	7	8	9	
DICCZ	4	5	6	7	8	9	10	
	5	6	7	8	9	10	11	
	6	7	8	9	10	11	12	

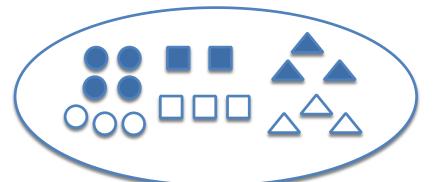
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6	6	12

• If we roll two fair dice, what is the most probable value obtained when we sum their outcomes?



#### **Unconditional/Conditional/Joint Probability**

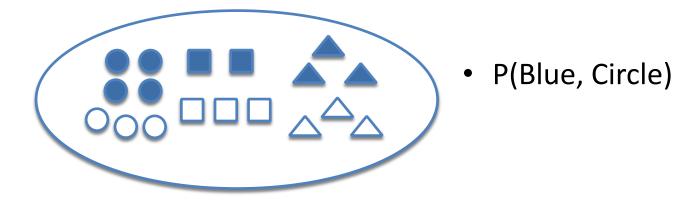
- Unconditional/Prior probability: degrees of belief in propositions in the absence of any other information
  - Example P(Sum = 11)
- Conditional/Posterior probability: degrees of belief in propositions given other information (evidence)
  - $P(A \mid B)$ : the conditional probability that A is true given that B is true
  - Example  $P(Sum = 11 | Die_1 = 6)$ , the conditional probability that the total number is 11 given that the first dice outcome is 6
- Joint probability  $P(A, B) ::= P(A \cap B)$ : the probability that <u>A is true and B is true</u>



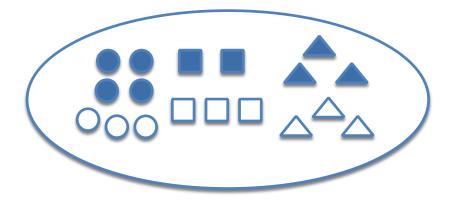
A sample space; in this example all outcomes have equal probability

**S**hape

		Circle	<mark>S</mark> quare	Triangle
Colour	Blue			
	White			



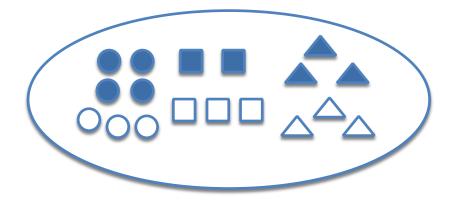
		Circle	<mark>S</mark> quare	Triangle	
Colour	Blue	4	2	3	9
	White	3	3	3	9
		7	5	6	18



• P(Blue, Circle) = 4 / 18

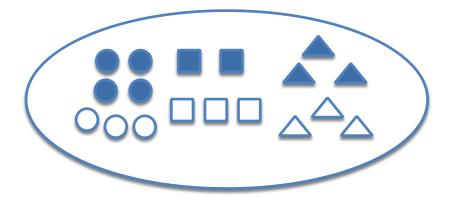
#### **S**hape

		Circle	<mark>S</mark> quare	Triangle	
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		7	5	6	18



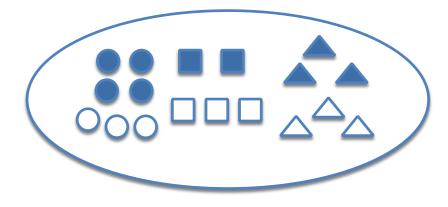
- P(Blue, Circle) = 4 / 18
- P(White, Square)

		Circle	Square	Triangle	
Colour	Blue	4	2	3	9
	White	3	3	3	9
		7	5	6	18



- P(Blue, Circle) = 4 / 18
- P(White, Square) = 3 / 18

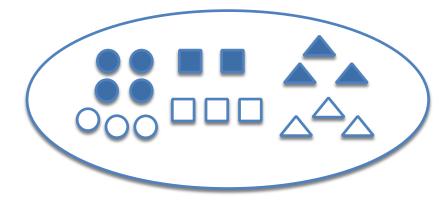
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		7	5	6	18



- P(Blue, Circle) = 4 / 18
- P(White, Square) = 3 / 18
- P(Circle)

Shape
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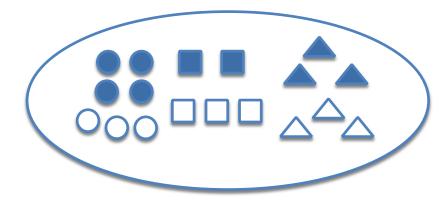
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<b>C</b> olour	Blue	4	2	3	9
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		7	5	6	18



- P(Blue, Circle) = 4 / 18
- P(White, Square) = 3 / 18
- P(Circle) = 7 / 18

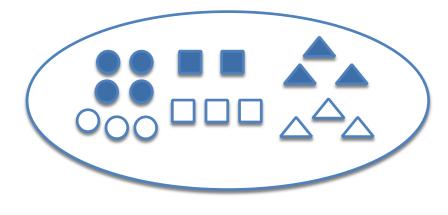
Shape
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		Circle	Square	Triangle	
<b>C</b> olour	Blue	4	2	3	9
	White	3	3	3	9
		7	5	6	18



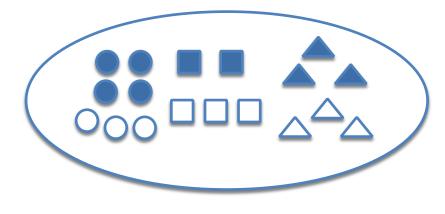
- P(Blue, Circle) = 4 / 18
- P(White, Square) = 3 / 18
- P(Circle) = 7 / 18
- P(Circle | Blue)

		Circle	<mark>S</mark> quare	Triangle	
Colour	Blue	4	2	3	9
	White	3	3	3	9
		7	5	6	18



- P(Blue, Circle) = 4 / 18
- P(White, Square) = 3 / 18
- P(Circle) = 7 / 18
- P(Circle | Blue) = 4 / 9

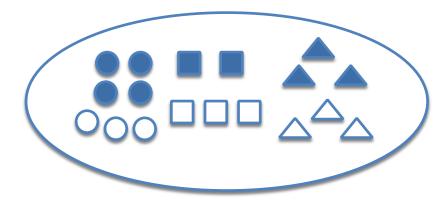
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	White	3	3	3	9
		7	5	6	18



- P(Blue, Circle) = 4 / 18
- P(White, Square) = 3 / 18
- P(Circle) = 7 / 18
- P(Circle | Blue) = 4 / 9
- P(Blue | Triangle)

**Shape** 

		<u>C</u> ircle	<mark>S</mark> quare	Triangle	
<b>C</b> olour	Blue	4	2	3	9
	White	3	3	3	9
		7	5	6	18



- P(Blue, Circle) = 4 / 18
- P(White, Square) = 3 / 18
- P(Circle) = 7 / 18
- P(Circle | Blue) = 4 / 9
- P(Blue | Triangle) = 3 / 6

**S**hape

		<b>C</b> ircle	<mark>S</mark> quare	Triangle	
<b>C</b> olour	Blue	4	2	3	9
	White	3	3	3	9
		7	5	6	18

#### **Product Rule**

P(A,B) = P(B) \* P(A | B) = P(A) \* P(B | A)

- Check the propositions
  - Simultaneously: P(A, B)
  - One by one: P(B) \* P(A | B) or P(A) \* P(B | A)

Note that the product rule also means that

P(B|A) = P(A|B) \* P(B)/P(A)

P(A,B) = P(B) \* P(A | B) = P(A) \* P(B | A)

Shape							
		Circle	<mark>S</mark> quare	Triangle			
<b>C</b> olour	Blue	4	2	3	9		
	White	3	3	3	9		
		7	5	6	18		

- P(Blue, Circle) = 4 / 18
- P(Blue) = 9 / 18
- P(Circle | Blue) = 4 / 9
- P(Circle) = 7 / 18
- P(Blue | Circle) = 4 / 7

#### Law of Total Probability and Normalisation Rule

 Law of total probability: the probability that a random variable takes a certain value the sum of the joint probability of other variables over their values:

$$P(X = x) = \sum_{y \in \Omega} P(X = x, Y = y)$$

• The normalisation rule: the probabilities of all values a random variable can take sums to one:

$$\sum_{x} P(X = x) = 1$$
$$\sum_{x} P(X = x \mid Y = y) = 1$$

#### Independence

- The product rule: P(A, B) = P(B) \* P(A | B) = P(A) \* P(B | A)
- If A and B are independent  $(A \perp B)$  to each other, then
  - P(A | B) = P(A)
  - P(B | A) = P(B)
  - P(A, B) = P(A) \* P(B)
- Flip coins twice, flip1 and flip2 are independent
- Weather and crop yield are dependent

## **Independent or Dependent?**

- Rolling a die and flipping a coin?
- Flipping a coin twice?
- Picking colored balls from a bag without replacement?
- Medical diagnoses for brothers?
- A customer and the purchase of a product?

## Summary

- Uncertainty is present in almost every worthwhile problem/decision
- **Probability theory** can be used to quantify and find relations for uncertainty
- There are many online resources, examples:
  - Khan academy
  - A lecture at the University of Chicago (first few slides discuss frequentist vs Bayesian; we use Bayesian view)