

# Introduction to Artificial Intelligence



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**COMP307**

**Planning and Scheduling:  
Tutorial 2**

# Dispatching Rule

- **Dispatching Rule**: a rule to **select one action** in each state
  - Considering **ONLY the earliest** applicable actions (**non-delay**)
  - Assigning a priority to each earliest action by a **priority function**
    - Selecting the action with the **highest priority**
- An example: **Shortest Processing Time (SPT)**
  - Always select the shortest processing time
  - Priority of Process(o, m, t) is **-ProcTime(o)**



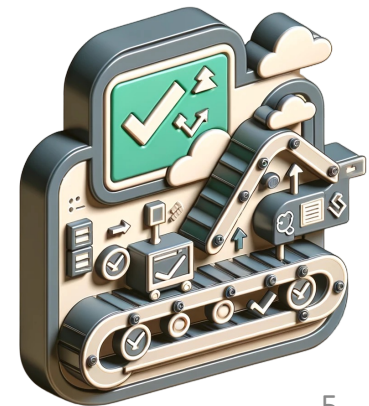
# Generate a Schedule by Dispatching Rule

- Step 1: Initialize state
  - empty schedule, all operations unprocessed, time = 0, machine idle
  - time = 0, first operation ready time = **arrival time**, other operation ready time =  $\infty$
- Step 2: Find the earliest applicable actions;
- **Step 3: Select the next action by the dispatching rule**
- Step 4: Add the selected action into the schedule, update the state
- Step 5: If all operations are processed, stop. Otherwise, go to step 2.



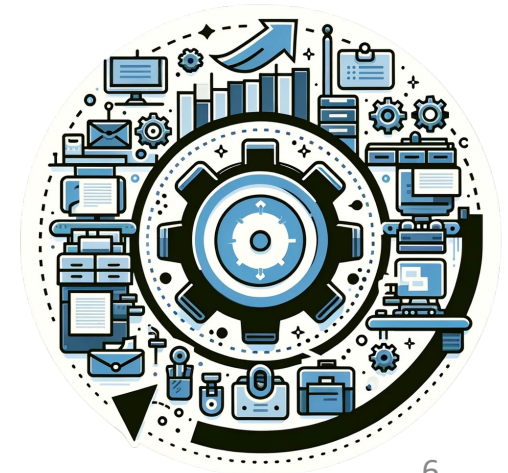
# Advantage of Dispatching Rule

- Can be apply at **ANY time point** to change the remaining schedule
  - Initial state = current state
  - But only need at **critical time point** (a machine becomes idle, an operation becomes ready)
- Select **ONLY** the **next action to be taken**, NO need to generate the entire remaining schedule
- Very **quick in real time**, can handle dynamic environment very well
  - At each time point, complexity = **#unprocessed ops \* O(priority)**



# Generate Schedule by SPT

	Arrive	ProcTime		
		AddEngine	AddWheels	Inspect
Job 1	0	30	30	10
Job 2	0	60	15	10
Job 3	10	20	30	10

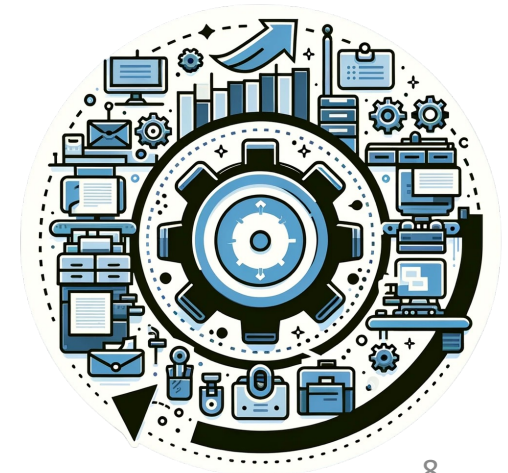


# Handwritten solution



# Generate Schedule by FCFS

	Arrive	ProcTime		
		AddEngine	AddWheels	Inspect
Job 1	0	30	30	10
Job 2	0	60	15	10
Job 3	10	20	30	10



# Handwritten solution



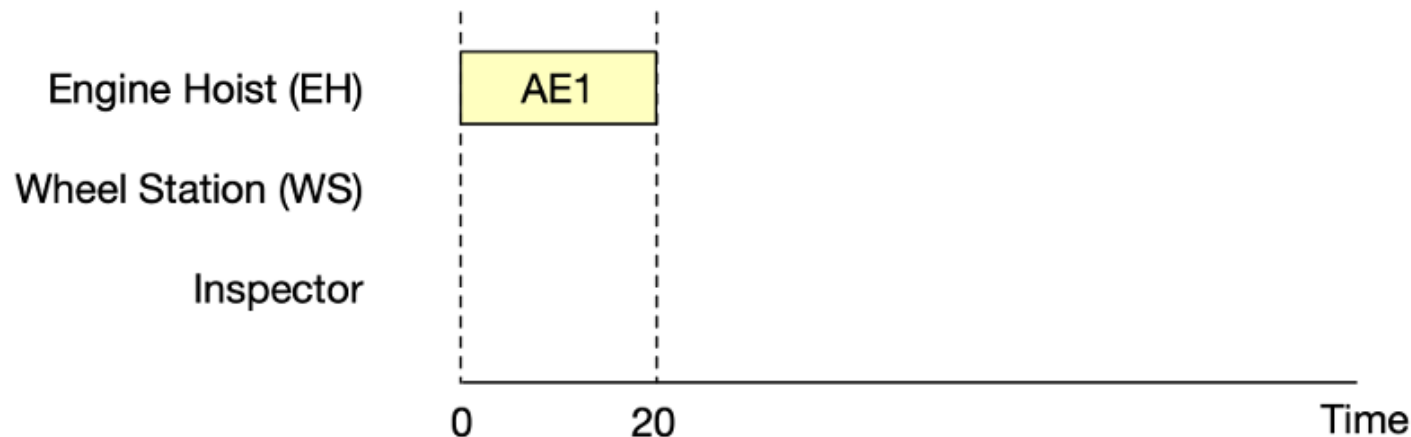


# Question

- For the car manufacturing scheduling problem, consider 3 jobs as summarized below:

	Arrival Time	Processing Time		
		AddEngine ( <i>AE</i> )	AddWheels ( <i>AW</i> )	Inspect ( <i>Ins</i> )
Job 1	0	20	30	15
Job 2	0	45	20	20
Job 3	10	25	30	10

- Given the partial schedule below:



- Select the next action by the Shortest Processing Time (SPT) rule. Show your working.

# Vehicle Routing



- Problem:
  - A **graph** with the **node** set and the **edge** set
  - A special **depot** node
  - Each **edge has a cost** (length, travel time, ...)
  - Each node except depot has a **demand** (customer demand)
  - Vehicles with limited **capacity**
- Find a **solution**:
  - A set of **routes**, each for a vehicle
  - Each node is **visited exactly once**
  - Each route starts and ends at the depot (**cycle**)
  - The total demand of the nodes in each route **does not exceed capacity**
- **Objective**: minimize the **total cost** of the routes

# Vehicle Routing is Hard

- Too many solutions
  - 10 nodes (excluding depot), 1 vehicle (TSP)
  - 3.6 million solutions
- **NP-hard**
  - Cannot guarantee to find the optimal solution in reasonable time
- How to Solve Vehicle Routing
  - **Heuristics**: Search for a reasonably good solution in a given (short) time
  - Introduced two heuristics in the lectures:
    - Nearest Neighbor heuristic
    - Savings heuristic



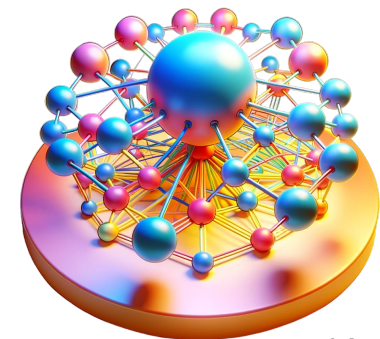
# Question

- For a vehicle routing problem with one depot and 5 customers (customer locations). Assume
  - Each customer has a demand of 1.
  - The maximum capacity of each car is 4.
- What is the total number of possible solutions to this vehicle routing problem?

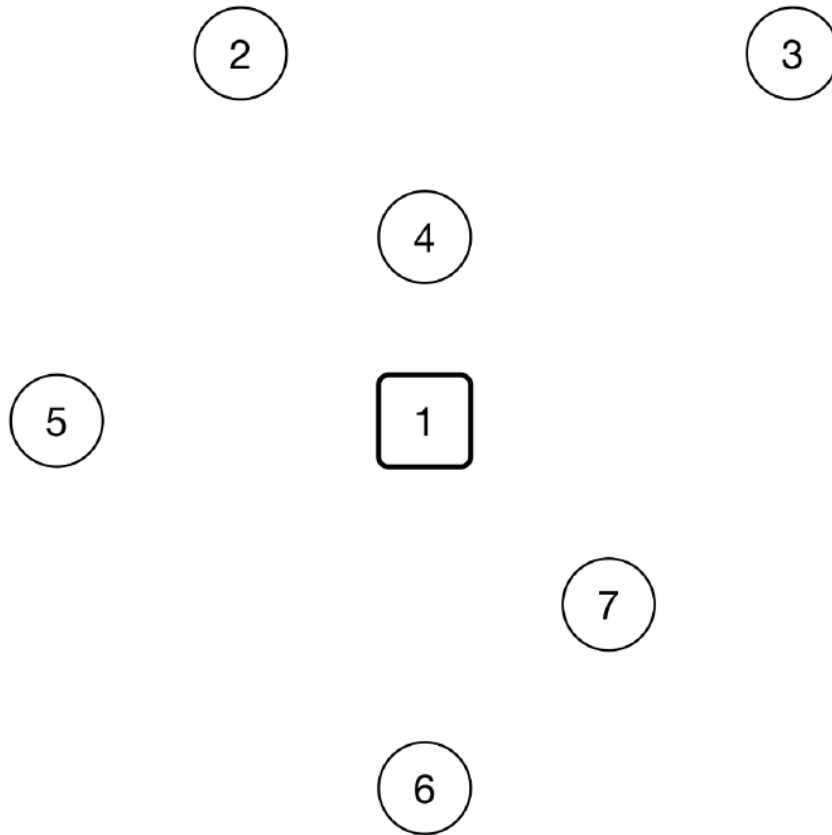


# Nearest Neighbor Heuristic

1. **Initialize** a solution: a route starting from the depot
2. Append the **nearest feasible node** to the end of the current route
  - **Unvisited**
  - After inserting the node, the total demand of the route **does not exceed the capacity**
3. If no feasible node is found for the current route, then **close the current route (return to the depot)** and create a **new route starting from the depot**
4. Repeat 2. and 3. until all nodes are visited



# Generate VRP Solution



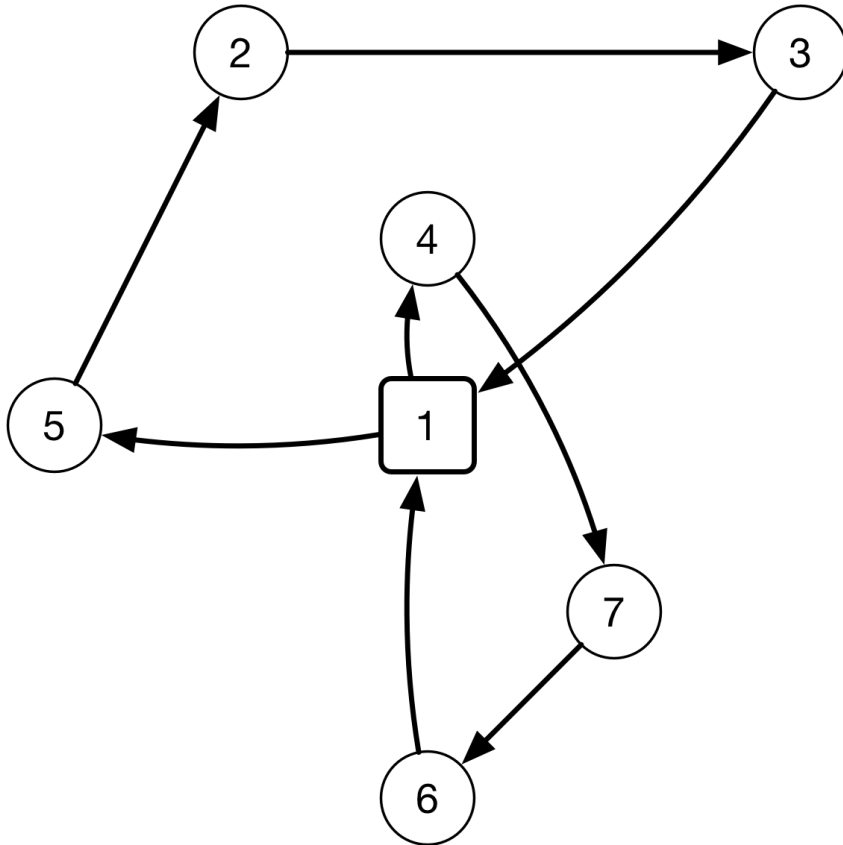
	1	2	3	4	5	6	7
1	0	2.2	2.8	1	2	2	1.4
2	2.2	0	3	1.4	2.2	4.1	3.6
3	2.8	3	0	2.2	4.5	4.5	3.2
4	1	1.4	2.2	0	2.2	3	2.2
5	2	2.2	4.5	2.2	0	2.8	3.2
6	2	4.1	4.5	3	2.8	0	1.4
7	1.4	3.6	3.2	2.2	3.2	1.4	0

**Capacity = 3**

# Handwritten solution



# Savings Heuristic



Feasible merges

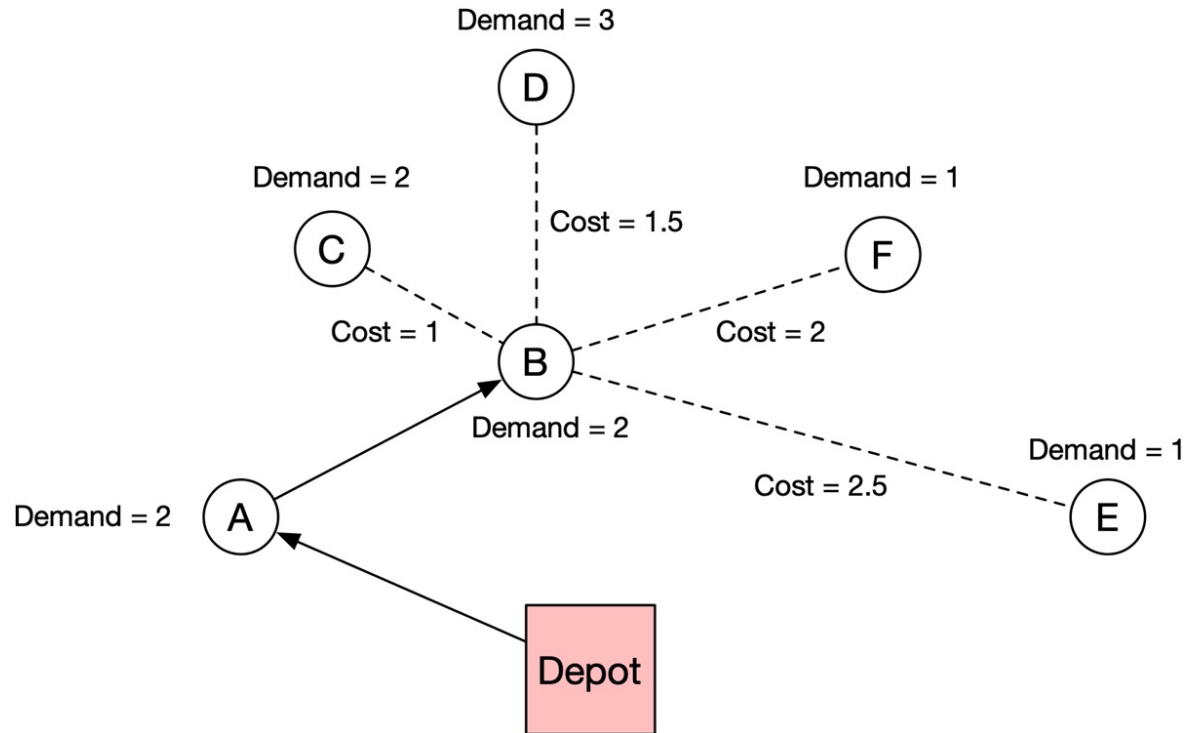
Merge	Sav
<del>(2,3)</del>	<del>2</del>
<del>(2,5)</del>	<del>2</del>
<del>(3,7)</del>	<del>2</del>
<del>(2,4)</del>	<del>1.8</del>
<del>(3,4)</del>	<del>1.6</del>
...	...
<del>(4,7)</del>	<del>0.2</del>
...	...

Merge	Sav
(2,3)	2
(2,5)	2
(6,7)	2
(2,4)	1.8
(3,4)	1.6
...	...
(4,7)	0.2
...	...



# Question

- Consider the vehicle routing with the partial solution [Depot, A, B]. Assume
  - Vehicle capacity is 5
  - Remaining nodes to visit is C, D, E, and F
  - Use the nearest neighbor heuristic



- List the next two steps (nodes to visit) selected by the nearest neighbor heuristic.