## ENGR101: Lecture 18

C++ classes, high-level software design

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# What we cover today?

- Group variables and function together C++ classes
- How to design big programs?



Classes in C++. Organizing your code.

We discussed **struct** before - customized data type. **struct** is similar to **Objects**.

In COMP102 you went through **Object-Oriented programming**. Is it applicable to C++?

Sure. There are very little differences between C++ and Java in that. OO programming is a good way to organize your data when it is possible to separate data into objects (Camera and Motor objects make Robot, as an example).

We can group related functions and variable together.

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## As an example...

Class to describe image-processing part of the project:

### Listing 1: Camera

```
class Camera{
  // function declarations
  double measure_line();
  double measure_intersection();
//function implementation
double Camera::measure_line(){
  return 0.0:
double Camera:: measure_intersection(){
  return 0.1;
int main(){
  Camera camera;
  double err = camera.measure_line();
```

- We grouped all image-processing functions into one class
- Note semicolon at the end of class declaration
- Function implementations do not have to be inside class scope {..}. Scope resolution operator ::.
- Declare variable of the type **Camera**.
- Does not compile

# Accessing class members(public, private)

### Listing 2: Camera

```
class Camera{
public:
   double measure_line();
  double measure_intersection();
};
double Camera::measure_line(){
  return 0.0:
double Camera:: measure_intersection(){
  return 0.1;
int main(){
 Camera camera;
  double err = camera.measure_line();
```

class1.cpp

- To get access to class members (variables or functions) from outside the class - these members should be declared as public.
- Private variables can be by modified only by functions which are members of the class.
- Private functions can be called only by functions which are members of the class.

# Simple and not so good solution:

Listing 3: All public

```
class Motor{
public:
// data
  double v_left;
  double v_right;
 // functions
 void forward(double dist);
 void back(double dist);
void Motor::forward(double dist){
 //code here
int main(){
 Motor m1:
 m1. v_left = 99.0:
 m1. forward (34);
```

- Make everything public.
- Variables and functions are accessible now.
- Class went to another extreme - there is no data protecton
- It became equivalent to C++ struct

### Getter and setter functions

## Listing 4: Setter getter

```
#include <iostream>
class Motor{
 private:
   // data
   double v_left, v_right;
  // functions
  public:
    void set_v_left(double x){v_left=x;}
    double get_v_left(){ return v_leftx;}
    void forward(double dist);
void Motor::forward(double dist){
  //code here
int main(){
  Motor m1:
  m1. set_v_left (99.0);
  std::cout << m1.get_v_left();
```

- both variables are private now
- set\_v\_left function set value of v\_left
- get\_v\_left function returns value of v\_left
- Both these functions are public and can be called from outside of the class
- If function is short (one-liner), declaration and implementation can be combined inside the class body

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### Constructor

### Listing 5: Constructor

```
class Motor{
  private:
    double v_left, v_right;
  public:
   Motor();
   void set_v_left(double x){v_left=x;}
   double get_v_left(){return v_left;}
 };
Motor:: Motor() { //constructor
         v_{-}left = 78.0:
int main(){
  Motor m1; //constructor call
  std::cout << m1.get_v_left();
class3.cpp
```

- It is not a good idea to leave declared variables not initialized
- Values are random: likely0 but can be anything
- Constructor is special function in the class
- It is called when instance of class is created

### Class instance as member of other class

Listing 6: Class member

```
class AVC{
 private:
    Camera camera;
    Motor motor;
   // data
  public:
    void go();
};
void AVC::go(){
  double err = camera.measure_line();
  motor.forward(45);
int main(){
 AVC avc;
  while (true){
   avc.go();
```

If variable motor is of type Motor (and is member of AVC) you can call Motor functions using .: motor.forward();. Recommended way is run one function from top class forever. That is what while (true) { ...} does.

class4.cpp

### Can we draw software structure?

Flow chart shows the algorithm.

It is not intended to represent code structure.

If you are using classes, there is a software to do high-level design.

Most widely used is **Universal Modelling Language**, UML for short. Its purpose is to provide visual representation of the software.

**Umbrello** is the software you can use. It is reasonably easy to use.

### Draw the class

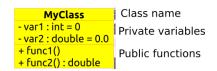
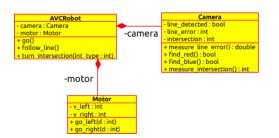


Figure: One class

- Each class in the program (can be many) is drawn as rectangle
- Variables are on the top, functions - in bottom part
- Private members are labeled with -, public with +

### Several classes



You can generate code from this diagram but I would not recommend it for now.

Figure: Class diagram

Note: Please do not use **Robot** as class name - it is already used in simulation library. Shown is just an example - your design can be totally different.

# Another type of chart - sequence diagram

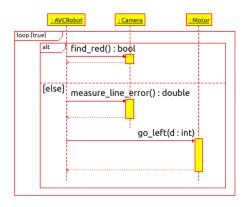


Figure: Sequence diagram

- Class diagram shows how your code is divided into pieces
- Sequence
   diagram shows
   how class
   functions are
   calling each other

# Is it compulsory to use?

Not at all.

Is it useful - yes. Start with flow chart - to visualize your algorithm. It is not a requirement to use classes but it helps.