

## **XMUT315 Control Systems Engineering**

# **Demo 5: Bode Plots Analysis**

Exercise 1 (Simulating Bode Plots)

Write a program in MATLAB to obtain a Bode plot for the transfer function:

a. The first system:

$$G(s) = \frac{15}{s(s+3)(0.7s+5)}$$

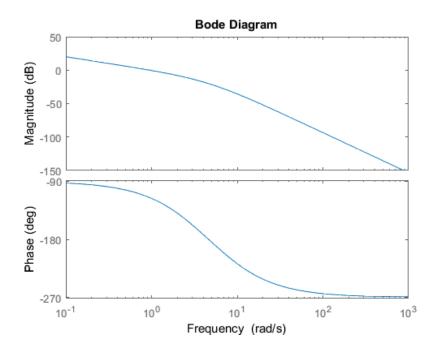
### **Solution**

The MATLAB program for simulating the bode plots of the given system is given below:

#### MATLAB code:

```
% demo51a.m
% Bode plot generation
clf
num=15;
den=conv([1 0],conv([1 3],[0.7 5]));
bode(num,den)
```

Computer response of the Bode plot simulation is shown in the figure below.



b. The second system:

$$G(s) = \frac{7s^3 + 15s^2 + 7s + 80}{s^4 + 8s^3 + 12s^2 + 70s + 110}$$

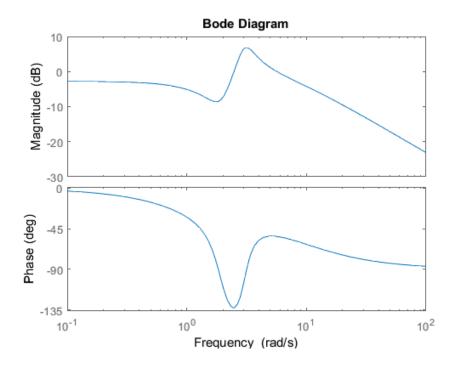
### **Solution**

The MATLAB program for simulating the Bode plots of the given system is given below:

#### MATLAB code:

```
% demo51b.m
% Simulate Bode plot
clf
num=[0 7 15 7 80];
den=[1 8 12 70 110];
bode(num,den)
```

Computer response of the Bode plot is shown in the figure given below.



Exercise 2 (Gain and Phase Margin in Bode Plots)

Write a program in MATLAB for the unity feedback system with the following transfer function:

$$G(s) = \frac{K}{s(s+3)(s+12)}$$

In this system, the value of gain K can be input. Display the Bode plots of the system for an input value of K. Determine and plot the gain and phase margin for an input value of K.

#### **Solution**

The MATLAB program for calculating the gain and phase margins of the given system is given below.

### MATLAB code:

```
% demo52a.m
% Simulate Bode plot and calculate gain and phase margins of the system
% Enter G(s)
numg=1;
deng=poly([0 -3 -12]);
'G(s)'
G=tf(numg,deng)
```

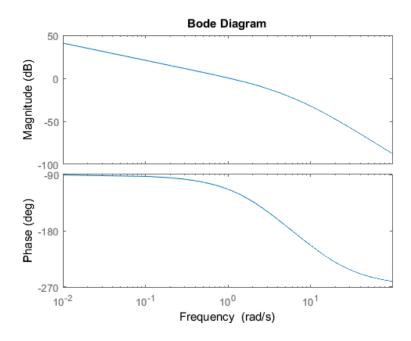
```
w=0.01:0.1:100;
% Enter K
K=input('Type gain, K = ');
bode (K*G, w)
pause
[M,P] = bode(K*G,w);
% Calculate gain margin
for i=1:1:length(P);
      if P(i) <=-180;
            fprintf('\nGain K = %g',K)
            fprintf(', Frequency (180 deg) = %g', w(i))
            fprintf(', Magnitude = %g',M(i))
            fprintf(', Magnitude(dB) = %g',20*log10(M(i)))
            fprintf(', Phase = %g',P(i))
            Gm=20*log10(1/M(i));
            fprintf(', Gain margin(dB) = %g',Gm)
            break
      end
end
% Calculate phase margin
for i=1:1:length(M);
      if M(i) <=1;
            fprintf('\nGain K = %g',K)
            fprintf(', Frequency(0 dB) = %g', w(i))
            fprintf(', Magnitude=%g',M(i))
            fprintf(', Magnitude(dB) = %g',20*log10(M(i)))
            fprintf(', Phase = %g',P(i))
            Pm=180+P(i);
            fprintf(', Phase margin(dB) = %g',Pm)
            break
      end
end
```

Type gain, K = 40 and the computer response:

Continuous-time transfer function.

Gain K = 40, Frequency (180 deg) = 6.01, Magnitude = 0.0738277, Magnitude(dB) = -22.6356, Phase = -180.076, Gain margin(dB) = 22.6356 Gain K = 40, Frequency(0 dB) = 1.11, Magnitude=0.93481, Magnitude(dB) = -0.585534, Phase = -115.589, Phase margin(dB) = 64.4107

## The Bode plot is shown in the figure given below.



The alternative MATLAB program for calculating the gain and phase margins of the given system is shown below:

## MATLAB code:

- % demo52b.m
- $\ensuremath{\text{\%}}$  Alternative program using MATLAB margin function

clear clf

```
% Bode plot and find points
%Enter G(s)
numg=1;
deng=poly([0 -3 -12]);
'G(s)'
G=tf(numg,deng)
w=0.01:0.1:100;
% Enter K
K=input('Type gain, K = ');
bode(K*G,w)

[Gm,Pm,Wcp,Wcg]=margin(K*G)
'Gm(dB)'
20*log10(Gm)
```

The outcome of the alternative MATLAB program using alternative approach is shown below:

Continuous-time transfer function.

Gm =

13.5000

Pm =

65.8119

Wcp =

6

Wcg =

1.0453

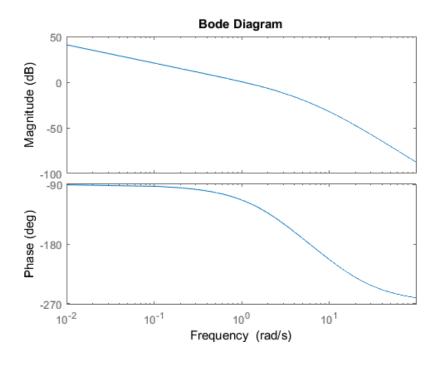
ans =

'Gm(dB)'

ans =

22.6067

The Bode plot of the alternative approach is shown in the figure given below.



### Exercise 3 (Peak Gain and Bandwidth of Bode Plot)

Write a program in MATLAB for the system shown below so that the value of K can be input (e.g. entering the value of K = 40 later).

$$\frac{C(s)}{R(s)} = \frac{K(s+5)}{s(s^2+3s+15)}$$

Display the closed-loop gain and phase frequency response for unity feedback system with an open-loop transfer function, KG(s).

Determine and display the peak gain, frequency of the peak gain, and bandwidth for the closed-loop frequency response for the input value of K.

#### Solution

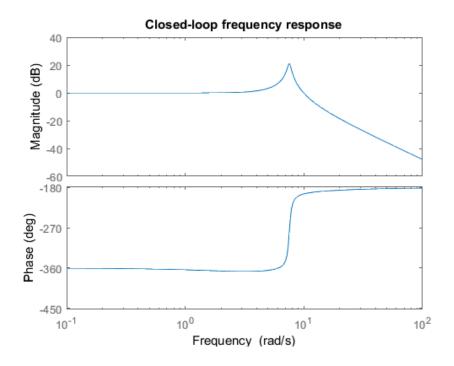
The MATLAB program for simulating the Bode plot and calculating the frequency response parameters of the system is given below.

#### MATLAB code:

```
% demo53.m
% Simulate the Bode plots and frequency response parameters of the system
% Enter G(s)
numg=[1 5];
deng=[1 3 15 0];
'G(s)'
G=tf(numg,deng)
% Enter K
K=input('Type gain, K = ');
'T(s)'
T=feedback(K*G,1)
bode (T)
title('Closed-loop frequency response')
[M,P,w] = bode(T);
[Mp i] = max(M);
MpdB=20*log10(Mp)
```

```
wp=w(i)
for i=1:1:length(M);
      if M(i) \le 0.707;
             fprintf('Bandwidth = %g',w(i))
      end
end
Type gain, K = 40 in the command prompt and the computer response is shown below:
ans =
     'T(s)'
T =
          40 s + 200
  s^3 + 3 s^2 + 55 s + 200
Continuous-time transfer function.
Mp =
    11.1162
MpdB =
   20.9192
wp =
    7.5295
Bandwidth = 11.2549:
```

The Bode plot of the system is shown in the figure given below.



## Exercise 4 (Analysis of Gain and Phase Margins in Bode plots)

The open-loop transfer function of a unity-feedback control system is given:

$$G(s) = \frac{K}{s(s^2 + 2s + 5)}$$

- a. Determine the value of gain K such that the phase margin is 50°.
- b. Find the gain margin for the gain K obtained in part (a).

## Solution

a. The closed loop transfer function of the system is:

$$\frac{C(s)}{R(s)} = \frac{K}{s^3 + 2s^2 + 5s + K}$$

The MATLAB code for simulating the Bode plot with K=1 is as follows:

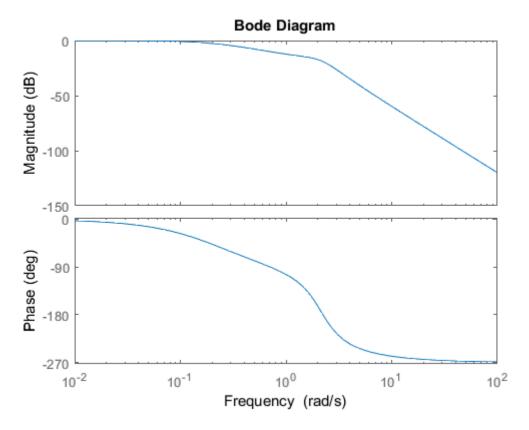
#### MATLAB code:

- % demo54a.m
- % Simulate Bode plot for determining value of system gain

clf

```
num=[1];
den=[1 2 5 1];
bode(num,den)
```

The Bode diagram is shown in the figure given below from MATLAB program.



a. From the Bode plot on the figure given above, the required phase margin of 50° and occurs at the frequency  $\omega = 1.5$  rad/s. The gain of  $G(j\omega)$  at this frequency is then -12 dB. To compensate for this gain, the gain K must then satisfy:

$$20\log K = 12 dB$$

As a result, the gain of the system, K=4 for the required phase margin of the system = 50°.

The MATLAB code for simulating the Bode plot with K=4 is as follows:

## MATLAB code:

```
% demo54b.m
% Simulate Bode plot for determining value of system gain
clf
num=[4];
den=[1 2 5 4];
```

bode(num, den)

The result of the Bode plot simulation of the system with K=4 given below shows that the phase margin of the system =  $50^{\circ}$  and the gain margin is at 0 dB.

